

7/27/04

07-29-2004



102801462

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

In re application of)	
D. McCALL, et al.)	
Serial No.: 09/458,175)	Attn: BOX ASSIGNMENTS
Filed: December 9, 1999)	
Patent No.: US 6,591,239 B1)	
Issued: July 8, 2003)	
For: VOICE CONTROLLED)	
SURGICAL SUITE WITH)	
MANUAL OVERRIDE AND)	
CONTROL, THE)	
APPARATUS INCLUDING)	
SURGICAL TABLE)	
LIGHTHEAD, TASK)	
LIGHT, AND CAMERA)	
Attorney Docket No.:)	Cleveland, OH 44114
MEDZ 2 01129 / 022001-001700US)	July 22, 2004

2004 JUL 27 AM 7:30
OPR/FINANCE

ASSIGNMENT TRANSMITTAL LETTER

Commissioner For Patents
P.O. Box 1450
Alexandria, VA 22313-1450

Dear Sir:

Please record the attached original document(s) or copy(ies) thereof.

1. Name of Party(ies) conveying an interest:

AGILITY CAPITAL LLC
229 East Canon Perdido
Suite F
Santa Barbara, CA 93101

2. Name of Party(ies) receiving an interest:

COMPUTER MOTION, INC.
570 Kifer Road
Sunnyvale, CA 94086

07/28/2004 NBETACHE 00000012 09458175

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40.00 DP

3. Description of the interest conveyed:
 Assignment Change of Name
 Security Agreement Merger
Other: Release of Security Interest and Quit Claim Assignment
4. This document is being filed in connection with U.S. Patent No. US 6,591,239 B1 issued July 8, 2003.
5. Name and address of Party to whom correspondence concerning this document should be mailed:

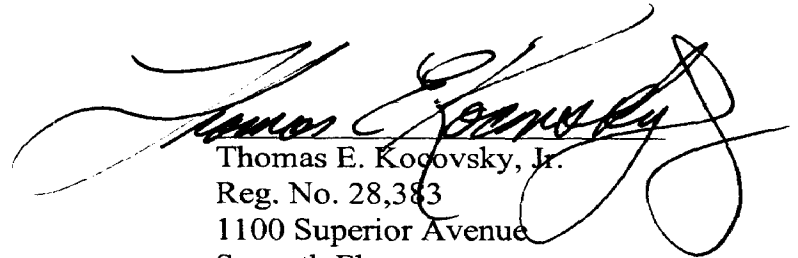
Thomas E. Kocovsky, Jr., Reg. No. 28,383
FAY, SHARPE, FAGAN MINNICH & McKEE, LLP
1100 Superior Avenue, Seventh Floor
Cleveland, Ohio 44114-2518

6. One patent is involved.
7. Amount of fee enclosed or authorized to be charged:
\$ 40.00
8. Deposit Account Number (attached duplicate copy of this form if paying by Deposit Account): 06-0308.
9. The Assignment shows it was signed on:
April 28, 2004 on behalf of AGILITY CAPITAL LLC.
10. To the best of my knowledge and belief, the foregoing information is true and correct and any attached copy is a true copy of the original document.

Total Number of pages including cover sheet (3 pages); and document (4 pages); Total: 7 pages.

Respectfully submitted,

FAY, SHARPE, FAGAN,
MINNICH & McKEE, LLP



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Reg. No. 28,383
1100 Superior Avenue
Seventh Floor
Cleveland, OH 44114-2518
(216) 861-5582

**RELEASE OF SECURITY INTEREST AND QUIT-CLAIM ASSIGNMENT
OF INTELLECTUAL PROPERTY**

WHEREAS, AGILITY CAPITAL LLC, of 229 East Canon Perdido, Suite F, Santa Barbara, California 93101, hereinafter referred to as "Assignor," may have or once had a security interest and/or a claim of title to intellectual property rights in technology developed by Computer Motion, Inc., including some or all patents and patent applications listed in attached Schedule A;

WHEREAS, COMPUTER MOTION, INC., a corporation of the State of California, located at 570 Kifer Road, Sunnyvale, California 94086, hereinafter referred to as "Assignee," is desirous of clarifying and/or obtaining clear title to these Intellectual Property rights, and to rights, if any, of Assignor to patents and patent applications listed in Schedule A;

Now, therefore, Assignor and Assignee agree as follows:

Assignor has assigned, and by these presents does assign to Assignee all right, title, and interest in and to all intellectual property rights of Assignor, if any, pertaining to any intellectual property developed by the Assignee, including rights to patents and patent applications listed in Schedule A, and including rights to any inventions, patent applications, letters patent and/or registrations which have or may hereafter be granted thereon, trade secrets, know-how, copyright, designs, and the like, in the United States and Foreign Countries, and also including any and all rights Assignor might otherwise retain in the patent applications listed in the appended Schedule A.

Assignor and Assignee agree that any dispute or controversy arising out of or relating to any interpretation, construction, performance or breach of this agreement shall be settled by arbitration to be held in Santa Clara County, California, in accordance with the rules then in effect of the American Arbitration Association. The arbitrator may grant injunctions or other relief in such dispute or controversy. The decision of the arbitrator shall be final, conclusive and binding on the parties to the arbitration. Judgment may be entered on the arbitrator's decision in any court having jurisdiction. Assignor and Assignee shall each pay one-half of the costs and expenses of such arbitration, and each shall separately pay counsel fees and expenses.

IN TESTIMONY WHEREOF, Assignor and Assignee have signed their names on the dates indicated.

Dated: 4/28/04

Assignor:
Agility Capital LLC
By: [Signature]
RTS: Chief Executive Officer

Attachments: *Appendix A*

60202798 v1

Schedule A
(as attached to PTO/SB/82)

	Application No. Filing Date	Patent No. Issue Date	Title	Attorney Docket No.
1.	07/174653 03/29/1988	5019968 05/28/1991	Three Dimensional Vector Processor	022001-000100US
2.	07/553884 07/16/1990	5187796 02/16/1993	Three Dimensional Vector Co-Processor Having I, J, and K Register Files and I, J, K Execution Units	022001-000110US
3.	08/305415 09/13/1994	5515478 05/07/1996	Automated Endoscope System for Optimal Positioning	022001-000200US
4.	08/768103 12/16/1999	5754741 05/19/1998	Automated Endoscope System for Optimal Positioning	022001-000210US
5.	08/072982 06/03/1993	5524180 06/04/1996	Automated Endoscope System for Optimal Positioning	022001-000220US
6.	08/613866 03/11/1996	5907664 05/25/1999	Automated Endoscope System for Optimal Positioning	022001-000221US
7.	08/903955 07/31/1997	5841950 11/24/1998	Automated Endoscope System for Optimal Positioning	022001-000222US
8.	08/903914 07/31/1997	5815640 09/29/1998	Automated Endoscope System for Optimal Positioning	022001-000223US
9.	08/481926 06/06/1995	5657429 08/12/1997	Automated Endoscope System for Optimal Positioning	022001-000230US
10.	08/732015 10/16/1996	5878193 03/02/1999	Automated Endoscope System for Optimal Positioning	022001-000231US
11.	09/996419 11/28/2001		Automated Endoscope System for Optimal Positioning	022001-000233US
12.	08/346537 11/29/1994	5553198 09/03/1996	Automated Endoscope System for Optimal Positioning	022001-000241US
13.	08/529095 09/15/1995	5825982 10/20/1998	Head Cursor Control Interface for an Automated Endoscope System for Optimal Positioning	022001-000330US
14.	08/904047 07/31/1997	5911036 06/08/1999	Head Cursor Control Interface for an Automated Endoscope System for Optimal Positioning	022001-000331US
15.	09/179039 10/26/1998	6714841 03/30/2004	Head Cursor Control Interface for an Automated Endoscope System for Optimal Positioning	022001-000332US
16.	08/310665 09/22/1994	6463361 10/08/2002	Speech Interface for an Automated Endoscopic System	022001-000400US
17.	10/095488 03/11/2002		Speech Interface for an Automated Endoscopic System	022001-000401US
18.	08/322788 10/12/1994	5645520 07/08/1997	Shape Memory Alloy Actuated Rod for Endoscopic Instruments	022001-000500US
19.	08/603543 02/20/1996	5762458 06/09/1998	Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000800US
20.	09/000703 12/30/1997	6244809 06/12/2001	Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000802US
21.	09/000933 12/30/1997	6001108 12/14/1999	Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000803US
22.	09/014698 01/28/1998	5971976 10/26/1999	Motion Minimalization and Compensation System for Use in Surgical Procedures	022001-000805US
23.	10/067730 02/04/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000811US
24.	09/953418 09/14/2001		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000820US

Schedule A
(as attached to PTO/SB/82)

25.	08/755063 11/22/1996	5855583 01/05/1999	Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000830US
26.	09/168527 10/08/1998	6007550 12/28/1999	Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000831US
27.	10/289740 11/06/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000833US
28.	08/873190 08/15/2000	6102850 08/15/2000	Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000840US
29.	09/557950 04/24/2000	6699177 03/02/2004	Method and Apparatus for Performing Minimally Invasive Surgical Procedures	022001-000841US
30.	10/339077 01/07/2003		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000842US
31.	10/737195 12/15/2003		Medical Robotic Arm that is Attached to an Operating Table	022001-000843US
32.	10/313810 12/06/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000845US
33.	09/156994 09/18/1998	6063095 05/16/2000	Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000853US
34.	09/262134 03/03/1999	6436107 08/20/2002	Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000854US
35.	09/000934 12/30/1997		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000860US
36.	10/241139 09/10/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000861US
37.	10/241143 09/10/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000862US
38.	10/242168 09/11/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000863US
39.	10/310579 12/04/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000864US
40.	10/310405 12/04/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000865US
41.	10/310536 12/04/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000866US
42.	10/317890 12/11/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000867US
43.	08/669629 06/24/1996		Multi-Functional Surgical Control System and Switching Interface	022001-000899US
44.	08/929024 09/15/1997		Multi-Functional Surgical Control System and Switching Interface	022001-000901US
45.	10/722837 11/26/2003		Multi-Functional Surgical Control System and Switching Interface	022001-000902US
46.	08/693352 08/06/1996	6646541 11/11/2003	General Purpose Distributed Operating Room Control System	022001-000910US
47.	08/958916 10/28/1997	6642836 11/04/2003	General Purpose Distributed Operating Room Control System	022001-000911US
48.	09/354944 07/15/1999	6496099 12/17/2002	General Purpose Distributed Operating Room Control System	022001-000920US
49.	10/315893 12/09/2002		General Purpose Distributed Operating Room Control System	022001-000921US

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50.	09/615641 07/13/2000		Method and Apparatus for Accessing Medical Data Over a Network	022001-000930US
51.	10/666922 09/18/2003		General Purpose Distributed Operating Room Control System	022001-000940US
52.	09/287860 04/07/1999	6132441 10/17/2000	Rigidly-Linked Articulating Wrist With Decoupled Motion Transmission	022001-001000US
53.	10/013170 12/07/2001		Rigidly-Linked Articulating Wrist With Decoupled Motion Transmission	022001-001001US
54.	09/411442 10/01/1999		Heart Stabilizer	022001-001300US
55.	09/870331 05/29/2001		Heart Stabilizer	022001-001310US
56.	09/675824 09/29/2000		Heart Stabilizer Support Arm	022001-001500US
57.	09/639489 08/15/2000	6726699 04/27/2004	Universal Instrument Guide or Cannula for Endoscopic Surgery	022001-001600US
58.	09/458175 12/09/1999	6591239 07/08/2003	Voice Controlled Surgical Suite	022001-001700US
59.	09/847736 05/01/2001		Pivot Point Arm for a Robotic System Used to Perform a Surgical Procedure	022001-001900US
60.	10/411651 04/10/2003		Pivot Point Arm for a Robotic System Used to Perform a Surgical Procedure	022001-001910US
61.	09/935555 08/21/2001		Robotically Controlled Surgical Instrument, Visual Force-Feedback	022001-002000US
62.	09/949050 09/07/2001	6728599 04/27/2004	Modularity System for Computer Assisted Surgery	022001-002100US
63.	10/423432 04/24/2003		Modularity System for Computer Assisted Surgery	022001-002110US
64.	10/418403 04/17/2003		Modularity System for Computer Assisted Surgery	022001-002120US
65.	10/423429 04/24/2003		Modularity System for Computer Assisted Surgery	022001-002121US
66.	10/423431 04/24/2003		Modularity System for Computer Assisted Surgery	022001-002122US
67.	10/423428 04/24/2003		Modularity System for Computer Assisted Surgery	022001-002123US
68.	10/012602 12/08/2001		Multifunctional Handle for a Medical Robotic	022001-002200US
69.	10/013067 12/07/2001		Microwrist System for Surgical Procedures	022001-002300US
70.	10/006905 11/07/2001	6730021 05/04/2004	Tissue Spreader with Force Measurement, Force Indication or Force Limitation	022001-002600US
71.	10/051796 01/16/2002		Minimally Invasive Surgical Training Using Robotics and Tele-Collaboration	022001-002700US
72.	10/246236 09/17/2002		Tele-Medicine System that Transmits an Entire State of a Subsystem	022001-002710US
73.	10/460382 06/11/2003		Surgical Instrument With a Universal Wrist	022001-002800US