

PATENT ASSIGNMENT

Electronic Version v1.1
 Stylesheet Version v1.1

SUBMISSION TYPE:	NEW ASSIGNMENT
NATURE OF CONVEYANCE:	ASSIGNMENT
CONVEYING PARTY DATA	
Name	Execution Date
Thenkurussi Kesavadas	06/19/2013
RECEIVING PARTY DATA	
Name:	The Research Foundation for The State University of New York
Street Address:	University at Buffalo, Office of Science, Technology Transfer and Economic Outreach
Internal Address:	Baird Research Park, Suite 111, 1576 Sweet Home Road
City:	Amherst
State/Country:	NEW YORK
Postal Code:	14228
PROPERTY NUMBERS Total: 1	
Property Type	Number
Application Number:	13806889
CORRESPONDENCE DATA	
Fax Number:	7168490349
<i>Correspondence will be sent via US Mail when the fax attempt is unsuccessful.</i>	
Phone:	716.856.4000
Email:	rwatt@hodgsonruss.com
Correspondent Name:	Rachel S. Watt
Address Line 1:	Hodgson Russ LLP
Address Line 2:	140 Pearl Street, Suite 100
Address Line 4:	Buffalo, NEW YORK 14202-4040
ATTORNEY DOCKET NUMBER:	003551.00510
NAME OF SUBMITTER:	Rachel S. Watt
Signature:	/rachel s. watt#46186/
Date:	07/17/2013
Total Attachments: 2 source=Kesh Assignment#page1.tif source=Kesh Assignment#page2.tif	

CH \$40.00 13806889

ASSIGNMENT

In consideration of One Dollar (\$1.00), and other good and valuable consideration, the receipt of which is hereby acknowledged, **Thenkurussi Kesavadas**, residing at 9030 Michael Douglas Drive, Clarence Center, New York 14032, the undersigned

Hereby sells, assigns and transfers to **The Research Foundation for The State University Of New York**, having a place of business at University at Buffalo, Office of Science, Technology Transfer and Economic Outreach, Baird Research Park, Suite 111, 1576 Sweet Home Road, Amherst, New York 14228, its successors, assigns and legal representatives, the entire right, title and interest for the United States and all foreign countries, in and to any and all inventions disclosed in the following patent applications:

Country	Patent Application No.	Filing Date	Title
US	61/348,733	May 26, 2010	Method And System For Minimally-Invasive Surgery Training Using Automatic Tool Position Determination
WO	PCT/US2011/038206	May 26, 2011	Method And System For Automatic Tool Position Determination For Minimally-Invasive Surgery Training
US	13/806,889	December 26, 2012	Method And System For Automatic Tool Position Determination For Minimally-Invasive Surgery Training
Korea	10-2012-7033911	May 26, 2011	Method And System For Automatic Tool Position Determination For Minimally-Invasive Surgery Training
India	11197/DELNP/2012	May 26, 2011	Method And System For Automatic Tool Position Determination For Minimally-Invasive Surgery Training
EP	11787444.6	May 26, 2011	Method And System For Automatic Tool Position Determination For Minimally-Invasive Surgery Training

And in and to said applications and all application that claim priority to any of the
aforementioned applications including all divisional, continuation, reissue, and continuation-
in-part applications, or national or regional phase applications thereof, which have been or shall
be filed in the United States and all foreign countries on any of said inventions; and in and to all
original and reissued patents which have been or shall be issued in the United States and all
foreign countries on said improvements;

Agrees that said Assignee may apply for and receive Patents for said inventions in its
own name; and that, when requested, shall execute all rightful oaths or declarations, assignments,
powers of attorney and other papers; which said Assignee, its successors, assigns or
representatives shall consider desirable for aiding in securing and maintaining proper patent
protection for said inventions; and

Covenants with said Assignee, its successors, assigns and legal representatives that no
assignment, grant, mortgage, license or other agreement affecting the rights and property herein
conveyed has been made to others by the undersigned, and that full right to convey the same as
herein expressed is possessed by the undersigned.

Date: _____



6/19/2013

Thenkurussi Kesavadas