

PATENT ASSIGNMENT COVER SHEET

Electronic Version v1.1
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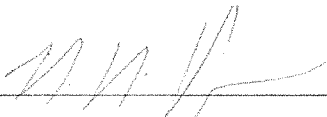
SUBMISSION TYPE:	NEW ASSIGNMENT
NATURE OF CONVEYANCE:	ASSIGNMENT
CONVEYING PARTY DATA	
Name	Execution Date
HEIKO HOFFMAN	06/19/2014
DAVID W. PAYTON	06/19/2014
DEREK MITCHELL	07/01/2014
RECEIVING PARTY DATA	
Name:	GM GLOBAL TECHNOLOGY OPERATIONS LLC
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State/Country:	MICHIGAN
Postal Code:	48265-3000
PROPERTY NUMBERS Total: 1	
Property Type	Number
Application Number:	14323047
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NAME OF SUBMITTER:	CHRISTOPHER W. QUINN
SIGNATURE:	/Christopher W. Quinn/
DATE SIGNED:	07/29/2014
Total Attachments: 2	
source=Assignment_P025343#page1.tif	
source=Assignment_P025343#page2.tif	

ASSIGNMENT

Pursuant to an agreement with my employer, I formally assign to GM GLOBAL TECHNOLOGY OPERATIONS LLC, the entire right, title and interest, in all countries and application types, in the improvements set forth in the United States patent application P025343-RD-SDJ entitled

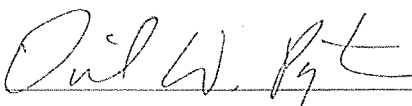
DYNAMICAL SYSTEM-BASED ROBOTIC VELOCITY CONTROL

for which I executed a declaration. If the patent application has been filed, I authorize any practitioner associated with Customer No. 72823 to insert the application number and filing date of said application here in parentheses (14/323047 filed 08-JUL-2014) when known.

Inventor's signature  Date 6-19-14

Full name : HEIKO HOFFMANN

Residence : SIMI VALLEY, CALIFORNIA

Inventor's signature  Date 6-19-14

Full name : DAVID W. PAYTON

Residence : CALABASAS, CALIFORNIA

Inventor's signature _____ Date _____

Full name : DEREK MITCHELL

Residence : CALABASAS, CALIFORNIA

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Inventor's signature _____ Date _____

Full name : HEIKO HOFFMANN
Residence : SIMI VALLEY, CALIFORNIA

Inventor's signature _____ Date _____

Full name : DAVID W. PAYTON
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Inventor's signature  Date 7/11/14

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