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Invention Title: A variable stiffness leg structure for multipede running robots

Inventor(s): Jonathan Clark, Kevin Galloway, Dan Koditschek

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Patent or Application Serial No.: 8,789,630

Grant/Contract Number(s): FIBR0425878

Foreign Applications filed/intended in (countries): _____

The invention identified above is a Subject Invention under 35 U.S.C. 200, et seq., and the Standard Patent Rights clause at 37 CFR 401.14, FAR 52.227-11 or FAR 52.227-12 (if applicable) which are included among the terms of the above identified grant or contract award from the United State Government. This document is confirmatory of:

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Signed this 22nd day of August, 2014.

By Kathryn A. Donohue *Kathryn A. Donohue*
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