

## PATENT ASSIGNMENT COVER SHEET

Electronic Version v1.1  
 Stylesheet Version v1.2

EPAS ID: PAT5297866

<b>SUBMISSION TYPE:</b>	NEW ASSIGNMENT	
<b>NATURE OF CONVEYANCE:</b>	ASSIGNMENT	
<b>CONVEYING PARTY DATA</b>		
	<b>Name</b>	<b>Execution Date</b>
	ROY SCOTT	12/19/2017
<b>RECEIVING PARTY DATA</b>		
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<b>Street Address:</b>	UNIT 2, CROME LEA BUSINESS PARK	
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<b>City:</b>	CAMBRIDGE	
<b>State/Country:</b>	UNITED KINGDOM	
<b>Postal Code:</b>	CB23 7PH	
<b>PROPERTY NUMBERS Total: 2</b>		
	<b>Property Type</b>	<b>Number</b>
	Application Number:	29674091
	Application Number:	29674092
<b>CORRESPONDENCE DATA</b>		
<b>Fax Number:</b>		
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<b>ATTORNEY DOCKET NUMBER:</b>	049595-520C01US-520C02US	
<b>NAME OF SUBMITTER:</b>	ERIN WEINLICK	
<b>SIGNATURE:</b>	/Erin Weinlick/	
<b>DATE SIGNED:</b>	12/21/2018	
<b>Total Attachments: 2</b>		
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source=049595-SCOTT-Assignment-Executed#page2.tif		

## ASSIGNMENT

**WHEREAS**, ROY SCOTT having a principal place of residence at C/O Cambridge Medical Robotics Limited, Unit 2, Crome Lea Business Park, Madingley Road, Cambridge, CB23 7PH, (hereinafter referred to as Assignor), is the sole and exclusive owner, by assignment, of the Patent Applications listed in *Schedule A*; and

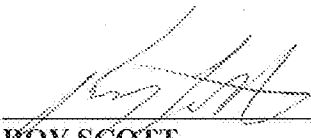
**WHEREAS**, Cambridge Medical Robotics Limited, a corporation organized under and pursuant to the laws of the United Kingdom having its principal place of business at Unit 2, Crome Lea Business Park, Madingley Road, Cambridge, CB23 7PH, United Kingdom (hereinafter referred to as Assignee), is desirous of acquiring the right, title and interest in, to and under said Patent Applications listed in *Schedule A* and the inventions covered thereby;

**NOW, THEREFORE**, for good and valuable consideration, receipt of which is hereby acknowledged, the said Assignor has sold, assigned, transferred and set over, and does hereby sell, assign, transfer and set over to the said Assignee, the entire right, title and interest for the United States of America and all other countries in and to said Patent Applications for all original, divisional, continuation, continuation-in-part, substitute or reissue applications and patents applied for or granted therefore in the United States of America and all other countries on the attached list of *Schedule A*, and the Commissioner of Patents and Trademarks is hereby authorized and requested to issue all patents on *Schedule A* to said Assignee herein, as Assignee of the entire interest therein; and the undersigned for itself and its legal representatives, heirs and assigns does hereby agree and covenant without further remuneration, to execute and deliver all divisional, continuation, continuation-in-part, reissue and other applications for Letters Patent and all assignments thereof to said Assignee or its assigns, to communicate to said Assignee or its representatives all facts known to the undersigned respecting said inventions listed on *Schedule A* whenever requested, to testify in any interferences or other legal proceedings in which said application or patent may become involved, to sign all lawful papers, make all rightful oaths, and do generally everything necessary to aid Assignee, its successors, assigns and nominees to obtain patent protection for said inventions listed on *Schedule A* in the United States of America and all other countries, the expenses incident to said application listed on *Schedule A* to be borne and paid by said Assignee.

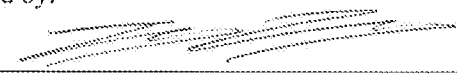
**SCHEDULE A**

<b>Application Number</b>	<b>Filing Date</b>	<b>Inventor</b>	<b>Title</b>	<b>Ctry</b>
29/627,992	November 30, 2017	Roy Scott	SURGICAL ROBOT ARM	US
29/627,993	November 30, 2017	Roy Scott	CART FOR SURGICAL ROBOT ARM	US
29/627,994	November 30, 2017	Roy Scott	CONSOLE FOR CONTROLLING SURGICAL ROBOT	US
29/627,995	November 30, 2017	Roy Scott	HAND CONTROLLER FOR CONTROLLING SURGICAL ROBOT	US

Date: 19 Dec 2017

  
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**ROY SCOTT**


Witnessed by:

  
\_\_\_\_\_  
Signature

19 DEC 2017  
\_\_\_\_\_  
Date

THOMAS JACKSON  
\_\_\_\_\_  
Print Name

Witnessed by:

  
\_\_\_\_\_  
Signature

19 DEC 2017  
\_\_\_\_\_  
Date

CHRISTOPHER ROACH  
\_\_\_\_\_  
Print Name