

PATENT ASSIGNMENT COVER SHEET

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EPAS ID: PAT5566272

SUBMISSION TYPE:	NEW ASSIGNMENT
NATURE OF CONVEYANCE:	ASSIGNMENT
CONVEYING PARTY DATA	
Name	Execution Date
SHENLONG WANG	05/20/2019
ANDREI POKROVSKY	05/27/2019
RAQUEL URTASUN SOTIL	06/11/2019
IOAN ANDREI BÂRSAN	05/21/2019
RECEIVING PARTY DATA	
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City:	SAN FRANCISCO
State/Country:	CALIFORNIA
Postal Code:	94103
PROPERTY NUMBERS Total: 1	
Property Type	Number
Application Number:	16437827
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ATTORNEY DOCKET NUMBER:	4872.092US1
NAME OF SUBMITTER:	KASIE GROVER
SIGNATURE:	/Kasie Grover/
DATE SIGNED:	06/11/2019
Total Attachments: 6	
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ASSIGNMENT

WHEREAS, Shenlong Wang, Andrei Pokrovsky, Raquel Urtasun Sotil and Ioan Andrei Bârsan (hereinafter the "Undersigned") have made one or more inventions and other subject matter (hereinafter collectively referred to as the "Invention"); as described in the patent application filed on June 11, 2019, assigned US application serial number 16/437,827, and titled AUTONOMOUS VEHICLE LOCALIZATION USING A LIDAR INTENSITY MAP and as described in a provisional patent application filed on June 15, 2018 assigned United States application serial number 62/685,875, and titled LEARNING TO LOCALIZE USING A LIDAR INTENSITY MAP.

FOR GOOD AND VALUABLE CONSIDERATION, the receipt, sufficiency, and adequacy of which are hereby acknowledged by the Undersigned, the Undersigned do hereby irrevocably and unconditionally:

CONVEY, ASSIGN, AND TRANSFER to Uber Technologies, Inc. (the "Assignee"), a corporation of the State of Delaware, having a place of business at 1455 Market Street, 4th Floor, San Francisco, CA 94103, the Undersigned's entire right, title, and interest for the United States and all foreign countries and jurisdictions in and to:

the Invention which is disclosed in the above-identified application or applications;

such application or applications, and all divisional, continuing (including continuation-in-part), substitute, renewal, reissue, and all other applications for a patent or patents which have been or shall be filed in the United States (including all provisional and non-provisional applications), and in all foreign countries and jurisdictions based in whole or in part on any of such Invention (including any application for a utility model or an innovation patent application);

all original and reissued patents which have been or shall be issued in the United States and all foreign countries and jurisdictions based in whole or in part on any of such Invention;

including the right to claim priority to the above-identified patent application or applications in relation to subject matter based in whole or in part on the above-identified patent application or applications and any of the foregoing including the right to file foreign applications under the provisions of any convention or treaty;

and including the right to all causes of action, remedies, and other enforcement rights related to the above-identified application or applications, including without limitation the right to sue for past, present, or future infringement, misappropriation, or violation of any and all rights related to the above-identified patent application or applications and any of the foregoing, including the right to obtain and collect damages for past, present, or future infringement;

AUTHORIZE AND REQUEST the issuing authority to issue any and all United States and foreign patents granted on such Invention to the Assignee;

AUTHORIZE AND REQUEST that any attorney associated with U.S. Patent and Trademark Office (USPTO) Customer No. 149714 may (directly or through his/her designee) delete, insert, or alter any

Assignment

Assignors: Shenlong Wang et al.

Title: AUTONOMOUS VEHICLE LOCALIZATION USING A LIDAR INTENSITY MAP

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information related to the above-identified patent application or applications or any of the foregoing, after execution of this Assignment;

WARRANT AND COVENANT that no assignment, grant, mortgage, license or other agreement affecting the rights and property herein conveyed has been or shall be made to others by the Undersigned, and that the full right to convey the same as herein expressed is possessed by the Undersigned;

COVENANT, that when requested and without compensation, but at the expense of the Assignee, in order to carry out in good faith the intent and purpose of this Assignment, the Undersigned shall (1) execute all provisional, non-provisional, divisional, continuing (including continuation-in-part), substitute, renewal, reissue, and all other patent applications for the Invention; (2) execute all rightful oaths, declarations, assignments, powers of attorney and other papers for the Invention; (3) communicate to the Assignee all facts known to the Undersigned relating to the Invention and the history thereof; (4) cooperate with the Assignee in any interference, reexamination, reissue, opposition, dispute, or litigation involving any of the applications or patents for the Invention; and (5) take such further actions as the Assignee shall reasonably consider necessary or desirable for vesting title to such Invention in the Assignee, or for securing, maintaining and enforcing proper patent protection for the Invention;

COVENANT, that should any provision of this agreement be held unenforceable by an authority of competent jurisdiction, such a ruling shall not affect the validity and enforceability of the remaining provisions.

THIS AGREEMENT IS TO BE BINDING on the heirs, assigns, representatives, and successors of the Undersigned, and is to extend to the benefit of the successors, assigns, and nominees of the Assignee.

AGREED as of the date of my signature below:

Assignment

Assignors: Shenlong Wang et al.

Title: AUTONOMOUS VEHICLE LOCALIZATION USING A LIDAR INTENSITY MAP

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Docket No: 4872.092US1
Client Ref. No. UP-00869US

Assignor:

(Signature):

/

Shenlong Wang

/

Name: Shenlong Wang

City/State or Country: Toronto, Canada

Date:

5/20/2019

Assignment

Assignors: Shenlong Wang et al.

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Docket No: 4872.092US1
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Assignor:

(Signature):

/

Andrei Pokrovsky

/

Name: Andrei Pokrovsky

City/State or Country: San Francisco, CA

Date:

5/27/2019

Assignment

Assignors: Shenlong Wang et al.

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Docket No: 4872.092US1
Client Ref. No. UP-00869US

Assignor:

(Signature):

/  /

Name: **Raquel Urtasun Sotil**

City/State or Country: **Toronto, Canada**

Date:

6/11/2019

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Assignors: Shenlong Wang et al.

Title: AUTONOMOUS VEHICLE LOCALIZATION USING A LIDAR INTENSITY MAP

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Docket No: 4872.092US1
Client Ref. No. UP-00869US

Assignor:

(Signature): / *Ioan Andrei Bârsan* /

Name: Ioan Andrei Bârsan

City/State or Country: Toronto, Ontario, Canada

Date: 5/21/2019