

PATENT ASSIGNMENT COVER SHEET

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SUBMISSION TYPE:	NEW ASSIGNMENT
NATURE OF CONVEYANCE:	ASSIGNMENT
CONVEYING PARTY DATA	
Name	Execution Date
HOPITAL DU VALAIS, CENTRE HOSPITALIER DU VALAIS ROMAND (CHVR)	02/25/2015
RECEIVING PARTY DATA	
Name:	KB MEDICAL, SA
Street Address:	2560 GENERAL ARMISTEAD AVENUE
City:	AUDUBON
State/Country:	PENNSYLVANIA
Postal Code:	19403
PROPERTY NUMBERS Total: 1	
Property Type	Number
Application Number:	16720187
CORRESPONDENCE DATA	
Fax Number:	(610)930-2042
<i>Correspondence will be sent to the e-mail address first; if that is unsuccessful, it will be sent using a fax number, if provided; if that is unsuccessful, it will be sent via US Mail.</i>	
Phone:	610-930-1800
Email:	Skyttle@globusmedical.com
Correspondent Name:	GLOBUS MEDICAL, INC.
Address Line 1:	VALLEY FORGE BUSINESS CENTER
Address Line 2:	2560 GENERAL ARMISTEAD AVENUE
Address Line 4:	AUDUBON, PENNSYLVANIA 19403
ATTORNEY DOCKET NUMBER:	ROBOT.027.0003
NAME OF SUBMITTER:	SUSAN KYTTLE
SIGNATURE:	/Susan Kyttle/
DATE SIGNED:	12/19/2019
Total Attachments: 2	
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Assignment

As part of an evaluation of the robotic system developed by KB Medical SA, certain employees of Hôpital du Valais, Centre Hospitalier du Valais Romand (CHVR) may have developed or contributed to certain inventions related to this evaluation. These employees include Dr Marc Morard and Dr Kristof Van Dommelen. They are co-inventors of the above mentioned system.

In consideration of this evaluation, or for other good and valuable consideration, the receipt of which is hereby acknowledged, Hôpital du Valais, CHVR confirms it has sold, assigned, and transferred or does hereby sell, assign, and transfer unto KB Medical SA, its entire right, title, and interest in and to any and all such inventions.

All costs related to patent applications filed as a result of this agreement, in particular application preparation, submission and maintenance will be borne by KB Medical SA.

Certain elements of evaluation-related invention are described in the Appendix to this assignment.

Hôpital du Valais

Prof. Eric Boivin
Directeur Général

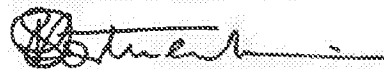
Sion, le 25/2/15

Prof. Mette M Berger
Coordinatrice de direction médicale
CHVR

Sion, le 17/01/15

KB Medical SA

Szymon Kostrzewski, PhD



Ecublens, le 2015-02-27

Appendix

Traditional open techniques for spinal surgeries are very invasive for the patient. They require relatively big opening which increases the risk of infections, tissue destruction and recovery time. Scars are big and reduce patient's comfort of life and appreciation of the procedure.

Several minimally invasive approaches to spinal surgeries were conceived, percutaneous technique being one of them. It looks to establish skin opening as small as possible by accessing inner organs via needle-puncture of the skin.

Percutaneous techniques are known in spinal surgeries. Some elements of this invention describe usage of the percutaneous technique in conjunction with robotic system. The basic workflow as initially designed with by the inventors is shown in Figure 1.

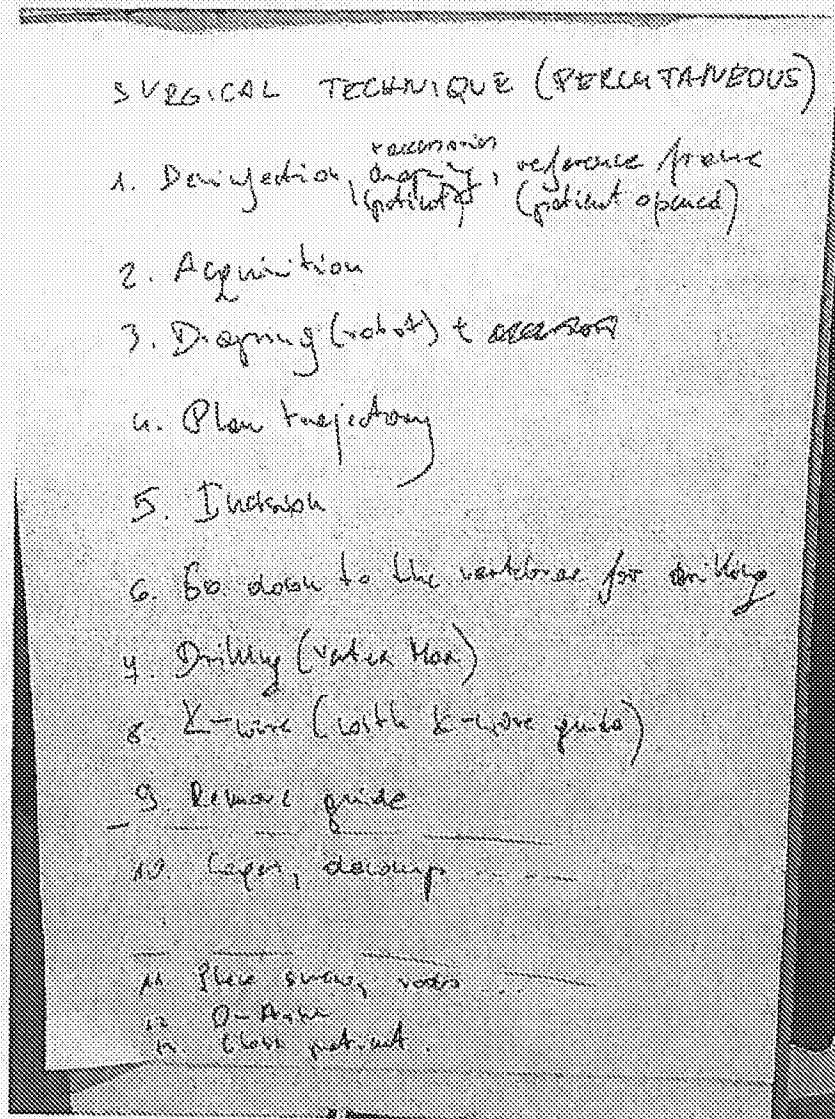


Figure 1: proposed workflow of percutaneous surgery using robotic system developed during meeting on 2014-12-08