506079896 05/28/2020

PATENT ASSIGNMENT COVER SHEET

Electronic Version v1.1 Stylesheet Version v1.2 EPAS ID: PAT6126612

SUBMISSION TYPE:	NEW ASSIGNMENT
NATURE OF CONVEYANCE:	ASSIGNMENT

CONVEYING PARTY DATA

Name	Execution Date
NOVARE SURGICAL SYSTEMS, INC.	08/02/2010

RECEIVING PARTY DATA

Name:	INTUITIVE SURGICAL OPERATIONS, INC.		
Street Address: 1266 KIFER ROAD			
City: SUNNYVALE			
State/Country: CALIFORNIA			
Postal Code:	94086		

PROPERTY NUMBERS Total: 1

Property Type	Number
Application Number:	16885787

CORRESPONDENCE DATA

Fax Number: (214)200-0853

Correspondence will be sent to the e-mail address first; if that is unsuccessful, it will be sent

using a fax number, if provided; if that is unsuccessful, it will be sent via US Mail.

Phone: 214-651-5000

Email: IPDOCKETING@HAYNESBOONE.COM

Correspondent Name: HAYNES AND BOONE, LLP Address Line 1: 2323 VICTORY AVENUE

Address Line 2: SUITE 700

Address Line 4: DALLAS, TEXAS 75219

ATTORNEY DOCKET NUMBER:	P01138-US-08
NAME OF SUBMITTER:	EFFEI DAH
SIGNATURE:	/Effei Dah/
DATE SIGNED:	05/28/2020

Total Attachments: 16

source=P01138-US-08 Executed Assignment [NVRE to ISRG] 70228.261US03#page1.tif source=P01138-US-08 Executed Assignment [NVRE to ISRG] 70228.261US03#page2.tif source=P01138-US-08 Executed Assignment [NVRE to ISRG] 70228.261US03#page3.tif source=P01138-US-08 Executed Assignment [NVRE to ISRG] 70228.261US03#page4.tif source=P01138-US-08 Executed Assignment [NVRE to ISRG] 70228.261US03#page5.tif

PATENT 506079896 REEL: 052776 FRAME: 0136

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source=P01138-US-08 Executed Assignment [NVRE to ISRG] 70228.261US03#page9.tif
source=P01138-US-08 Executed Assignment [NVRE to ISRG] 70228.261US03#page10.tif
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source=P01138-US-08 Executed Assignment [NVRE to ISRG] 70228.261US03#page16.tif

PATENT REEL: 052776 FRAME: 0137

Novare US Cases Assigned to Intuitive Surgical

11/181,445	7/13/2005	7,615,066	11/10/2009	ARTICULATING MECHANISM FOR REMOTE MANIPULATION OF A SURGICAL OR DIAGNOSTIC TOOL
12/10 9 ,333	4/24/2008			ARTICULATING INSTRUMENT
11/271,720	11/9/2005	7,682,307	3/23/2010	ARTICULATING MECHANISM FOR REMOTE MANIPULATION OF A SURGICAL OR DIAGNOSTIC TOOL
12/766,818	4/23/2010			ARTICULATING INSTRUMENTS WITH JOYSTICK CONTROL
12/766,820	4/23/2010			ARTICULATING MECHANISMS WITH BIFURCATING CONTROL
12/756,822	4/23/2010			ARTICULATING CATHETERS
12/766,825	4/23/2010			ARTICULATING ENDOSCOPES
12/766,827	4/23/2010			ARTICULATING RETRACTORS
10/997,249	11/24/2004	7,410,483	B/12/2008	HAND-ACTUATED DEVICE FOR REMOTE MANIPULATION OF A GRASPING TOOL
11/787,543	4/16/2007			TOOL WITH ARTICULATION LOCK
11/787,607	4/16/2007			TOOL WITH ROTATION LOCK
11/787,605	4/16/2007			TOOL WITH MULTI-STATE RATCHETED END EFFECTOR
11/787,599	4/16/2007			TOOL WITH END EFFECTOR FORCE LIMITER
11/787,608	4/16/2007			ARTICULATING TOOL WITH IMPROVED TENSION MEMBER SYSTEM
10/948,911	9/24/2004	7,678,117	3/16/2010	ARTICULATING MECHANISM WITH FLEX- HINGED LINKS
10/928,479	8/26/2004			LINK SYSTEMS AND ARTICULATION MECHANISMS FOR REMOTE MANIPULATION OF SURGICAL OF DIAGNOSTIC TOOLS

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Novare US Cases Assigned to Intuitive Surgical

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12/725,377	3/16/2010			ARTICULATING MECHANISM WITH FLEX- HINGED LINKS
12/816,359	6/15/2010			LINK SYSTEMS AND ARTICULATION MECHANISMS FOR REMOTE MANIPULATION OF SURGICAL OF DIAGNOSTIC TOOLS
11/121,668	5/3/2005			ARTICULATING MECHANISM COMPONENTS AND SYSTEM FOR EASY ASSEMBLY AND DISASSEMBLY
10/997,372	11/23/2004			ARTICULATING MECHANISMS AND LINK SYSTEMS WITH TORQUE TRANSMISSION IN REMOTE MANIPULATION OF INTRUMENTS AND TOOLS
11/122,598	5/4/2005	_		ARTICULATING MECHANISMS AND LINK SYSTEMS WITH TORQUE TRANSMISSION IN REMOTE MANIPULATION OF INSTRUMENTS AND TOOLS
10/997,245	11/23/2004			ARTICULATING SHEATH FOR FLEXIBLE INSTRUMENTS
12/542,589	8/17/2009			INSTRUMENT WITH ARTICULATION
12/508,478	7/23/2009			ARTICULATING MECHANISM
10/397915	3/25/2003	7588585	9/15/2009	HANDLELESS CLAMPING DEVICE
12/335431.	12/15/2008			HANDLELESS CLAMPING DEVICE
12/335452	12/15/2008			HANDLELESS CLAMPING DEVICE
12/335,462	12/15/2008			HANDLELESS CLAMPING DEVICE

IP ASSIGNMENT AGREEMENT

DATED AS OF

AUGUST 2, 2010

BETWEEN

NOVARE SURGICAL SYSTEMS, INC.

AND

INTUITIVE SURGICAL, INC.

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IP ASSIGNMENT AGREEMENT

This IP Assignment Agreement dated as of August 2, 2010 (this "Assignment"), by Novare Surgical Systems Inc., a Delaware corporation having its principal place of business at 10440 Bubb Road, Suite A, Cupertino, CA 95014 and its subsidiaries (together, "Assignor"), in favor of Intuitive Surgical Operations, Inc., a Delaware corporation having its principal place of business at 1266 Kifer Road, Sunnyvale, California 94086 and its subsididaries (together, "Assignee"). Each of Assignor and Purchaser shall be referred to herein as a "Party" and shall be collectively referred to as the "Parties." Capitalized terms that are used, whether in the singular or plural, shall have the meanings set forth in the Agreement (as defined below).

WITNESSETH:

WHEREAS, Assignor and Assignee are parties to that certain Asset Purchase Agreement, dated as of August 2, 2010 (the "Agreement"), pursuant to which Assignor has agreed to sell and transferred to Assignee and Assignee has agreed to purchase from Assignor certain assets including patents, trademarks, and copyrights.

WHEREAS, Assignor and Assignee wish to document by formal assignment to Assignee all of Assignor's title, interest, and rights in and to the patents, trademarks, and copyrights;

NOW, THEREFORE, in consideration of the mutual covenants and other good and valuable consideration described herein, the receipt and sufficiency of which are hereby acknowledged subject to the terms and conditions of the Agreement, the Parties hereto covenant and agree as follows:

- Assignment and Transfer of IP Rights. Subject to the terms and conditions of the Agreement, Assignor does hereby assign, Transfer, set over, and deliver to Assignee all of Assignor's rights, title, and interest in all Intellectual Property of or Controlled by Assignor that is set forth on schedules 1.1(a). Of this Assignment. Assignor further agrees, without further consideration, to cause to be performed such customary and lawful acts and to be executed such further assignments and other lawful documents as Assignee may reasonably request to effectuate fully this Assignment and to permit Assignee to be duly recorded as the registered owner and proprietor of the rights hereby conveyed.
- 2. <u>Consideration: Payment.</u> The consideration for this Assignment is detailed in the Agreement.

* * * * *

In WITNESS WRITTEGE, the undersigned has caused this Assignment to be executed by his signature as of the date above first written.

ASSIGNOR: NOVARE SURGICAL SYSTEMS, INC.

ACKNOWLEDGED AND ACCEPTED:

ASSIGNEE'S INTUITIVE SURGICAL OPERATIONS, INC.

Mame

Signature Page to Novare Surgecal Systems. IP Assignment Accounted

Schedule 1.1(a)

List of Assignor's Patent Portfolio Assigned to Assignee

10112- 701.201 10112- 701.301	USA
10112- 701.302	ASU
10112- 701.401	USA
10112- 701.402	ASU
10112- 701.403	USA
10112- 701,404	ASU
10112- 701.405	ASU
10112- 701.406	USA

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10112- 701.AU3	10112- 701.AU2	10112- 701.AU1	10112- 701.603	10112- 701.602	10112- 701.601	10112- 701.502	10112- 701.501
Australia	Australia	Australia	PCT	PCT	РСТ	USA	USA
ARTICULATING MECHANISM FOR REMOTE MANIPULATION OF A SURGICAL OR DIAGNOSTIC TOOL	HAND-ACTUATED DEVICE FOR REMOTE MANIPULATION OF A GRASPING TOOL	ARTICULATING MECHANISM FOR REMOTE MANIPULATION OF A SURGICAL OR DIAGNOSTIC TOOL	TOOL WITH ARTICULATION LOCK	HAND-ACTUATED DEVICE FOR REMOTE MANIPULATION OF A GRASPING TOOL	ARTICULATING MECHANISM FOR REMOTE MANIPULATION OF A SURGICAL OR DIAGNOSTIC TOOL	TOOL WITH ARTICULATION LOCK	HAND-ACTUATED DEVICE FOR REMOTE MANIPULATION OF A GRASPING TOOL
David J. Danitz, Adam Gold	David J. Danitz, Cameron Dale Hinman	David J. Danitz, Adam Goid	Cameron Dale Hinman, David Elias Hegeman, David J. Danitz, Lincoln J. Avord	David J. Danitz, Cameron Dale Hinman	David J. Danitz, Adam Gold	Cameron Dale Hinman, David Ellas Hegeman, David J. Danitz, Lincoln J. Alvord	David J. Danitz, Cameron Dale Hinman
2009243488	2005309974	2004243056	PCT/US2008/060385	PCT/US2005/033377	PCT/US2004/015944	11/787,543	10/997,249
5/21/2004	9/19/2005	5/21/2004	4/15/2008	9/19/2005	5/21/2004	4/16/2007	11/24/2004
Pending	Pending	Issued	Natl Ph	Nafl Ph	Nati Ph	Published	perss)

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10112- 701.EP3	10112- 701.EP2	10112- 701.EP1	10112- 701.CN3	10112- 701.CN2	10112- 701.CN1	10112- 701.CA2	10112- 701.CA1	10112- 701.BR1
Europe	Europe	Europe	China	China	China	Canada	Canada	Brazil
TOOL WITH ARTICULATION LOCK	HAND-ACTUATED DEVICE FOR REMOTE MANIPULATION OF A GRASPING TOOL	ARTICULATING MECHANISM FOR REMOTE MANIPULATION OF A SURGICAL OR DIAGNOSTIC TOOL	ARTICULATING MECHANISM FOR REMOTE MANIPULATION OF A SURGICAL OR DIAGNOSTIC TOOL	HAND-ACTUATED DEVICE FOR REMOTE MANIPULATION OF A GRASPING TOOL	ARTICULATING MECHANISM FOR REMOTE MANIPULATION OF A SURGICAL OR DIAGNOSTIC TOOL	HAND-ACTUATED DEVICE FOR REMOTE MANIPULATION OF A GRASPING TOOL	ARTICULATING MECHANISM FOR REMOTE MANIPULATION OF A SURGICAL OR DIAGNOSTIC TOOL	ARTICULATING MECHANISM FOR REMOTE MANIPULATION OF A SURGICAL OR DIAGNOSTIC TOOL
Cameron Dale Himman, David Elias Hegernan, David J. Danitz, Lincoln J. Alvord	David J. Danitz, Cameron Dale Hinman	David J. Danitz, Adam Goid	David J. Danitz, Adam Gold	David J. Danitz,Cameron Dale Hinman	David J. Danitz, Adam Gold	David J. Danitz, Cameron Dale Hinman	David J. Danitz, Adam Gold	David J. Danitz, Adam Gold
08745894.9	05798376.9	04752882.3	200910221710.6	200580047086.1	200480020940.1	2,588,286	2,526,381	PI0410599-0
4/15/2008	9/19/2005	5/21/2004	5/21/2004	9/19/2005	5/21/2004	9/19/2005	5/21/2004	5/21/2004
Published	Published	Published	Published	Issued	Issued	Pending	Pending	Published

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10112- 702.601	10112- 702.201	10112- 702.101	10112- 701.MX2	10112- 701.MX1	10112- 701.JP2	10112- 701.JP1	10112- 701.IN1	10112- 701.HK1
РСТ	USA	USA	Maxico	Mexico	Japan	Japan	India	Hong Kong
TOOL WITH ROTATION LOCK	TOOL WITH ROTATION LOCK	DEVICES HAVING LOCKING ROTATION KNOBS AND METHODS FOR USING THE SAME	ARTICULATING MECHANISM FOR REMOTE MANIPULATION OF A SURGICAL OR DIAGNOSTIC TOOL	ARTICULATING MECHANISM FOR REMOTE MANIPULATION OF A SURGICAL OR DIAGNOSTIC TOOL	HAND-ACTUATED DEVICE FOR REMOTE MANIPULATION OF A GRASPING TOOL	ARTICULATING MECHANISM FOR REMOTE MANIPULATION OF A SURGICAL OR DIAGNOSTIC TOOL	ARTICULATING MECHANISM FOR REMOTE MANIPULATION OF A SURGICAL OR DIAGNOSTIC TOOL	ARTICULATING MECHANISM FOR REMOTE MANIPULATION OF A SURGICAL OR DIAGNOSTIC TOOL
David J. Danitz, Cameron Dale Hinman	David J. Danitz, Cameron Dale Hinman	David J. Danitz, Cameron Dale Hinman	David J. Danitz, Adam Gold	David J. Danitz, Adam Gold	David J. Danitz, Cameron Dale Hinman	David J. Danitz, Adam Gold	David J. Danitz, Adam Gold	David J. Danitz, Adam Gold
PCT/US2007/070914	11/787,607	60/813,650	PA/a/2007/013992	PA/a/2005/012599	2007-543032	2006-533272	2298/KOLNP/2005	04752882.3
6/11/2007	4/16/2007	6/13/2006	5/21/2004	5/21/2004	9/19/2005	5/21/2004	5/21/2004	5/21/2004
Nati Ph	Published	Expired	Pending	Issued	Published	Pending	Issued	Published

706.202 USA	10112.	706.201	10112- LISA					
MANIPULATION OF SURGICAL OF DIAGNOSTIC TOOLS	LINK SYSTEMS AND ARTICULATION MECHANISMS FOR REMOTE	ARTICULATING MECHANISM WITH FLEX-HINGED LINKS		ARTICULATING MECHANISM WITH FLEX-HINGED LINKS	ARTICULATING TOOL WITH IMPROVED TENSION MEMBER SYSTEM ARTICULATING MECHANISM WELEX-HINGED LINKS	TOOL WITH END EFFECTOR FORCE LIMITER ARTICULATING TOOL WITH IMPROVED TENSION MEMBER SYSTEM ARTICULATING MECHANISM WITH FLEX-HINGED LINKS	TOOL WITH MULTI-STATE RATCHETED END EFFECTOR I TOOL WITH END EFFECTOR I LIMITER ARTICULATING TOOL WITH IMPROVED TENSION MEMBEI SYSTEM ARTICULATING MECHANISM FLEX-HINGED LINKS	TOOL WITH ROTATION LOCK TOOL WITH MULTI-STATE RATCHETED END EFFECTOR LIMITER ARTICULATING TOOL WITH IMPROVED TENSION MEMBE SYSTEM ARTICULATING MECHANISM FLEX-HINGED LINKS
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0/20/2004	25000	9/24/2004	6/7/2004		4/16/2007	4/16/2007	4/16/2007 4/16/2007 4/18/2007	6/11/2007 4/16/2007 4/16/2007 4/16/2007
r generico		Issued	Expired		Published	Published Published	Published Published	Published Published

5/23/2005	05754532.9	David J. Danitz, Carneron Dale Hinman	LINK SYSTEMS AND ARTICULATION MECHANISMS FOR REMOTE MANIPULATION OF SURGICAL OR DIAGNOSTIC TOOLS	Europe	10112- 706.EP2
	05754538.6	David J. Danitz, Cameron Dale Hinman	ARTICULATING MECHANISM WITH FLEX-HINGED LINKS	Europe	10112- 706.EP1
5	200580025154.5	David J. Danitz, Cameron Dale Hinman	LINK SYSTEMS AND ARTICULATION MECHANISMS FOR REMOTE MANIPULATION OF SURGICAL OR DIAGNOSTIC TOOLS	China	10112- 706.CN2
0	200580025153.0	David J. Danitz, Cameron Dale Hinman	ARTICULATING MECHANISM WITH FLEX-HINGED LINKS	China	10112- 706.CN1
46	PCT/US2005/018146	David J. Danitz, Cameron Dale Hinman	LINK SYSTEMS AND ARTICULATION MECHANISMS FOR REMOTE MANIPULATION OF SURGICAL OR DIAGNOSTIC TOOLS:	PCT	10112- 706.602
1 4	PCT/US2005/018145	David J. Danitz, Cameron Dale Hinman	ARTICULATING MECHANISM WITH FLEX-HINGED LINKS	PCT	10112- 706.601
	12/816,359	David J. Danitz Cameron Dale Hinman	LINK SYSTEMS AND ARTICULATION MECHANISMS FOR REMOTE MANIPULATION OF SURGICAL OF DIAGNOSTIC TOOLS	USA	10112- 706.302
	12/725,377	David J. Danitz,Cameron Dale Hinman	ARTICULATING MECHANISM WITH FLEX-HINGED LINKS	USA	10112- 706.301

10112- 707.CN1	10112- 707.CA1	10112- 707.601	10112- 707.201	10112- 707.101	10112- 706.JP2	10112- 706.JP1
China	Canada	РСТ	USA	USA	Japan	Japan
ARTICULATING MECHANISM COMPRISING PAIRS OF LINK COMPONENTS CONNECTED BY CABLES AND WHICH CAN BE EASILY ASSEMBLED	ARTICULATING MECHANISM COMPRISING PAIRS OF LINK COMPONENTS CONNECTED BY CABLES AND WHICH CAN BE EASILY ASSEMBLED	ARTICULATING MECHANISM COMPRISING PAIRS OF LINK COMPONENTS CONNECTED BY CABLES AND WHICH CAN BE EASILY ASSEMBLED	ARTICULATING MECHANISM COMPONENTS AND SYSTEM FOR EASY ASSEMBLY AND DISASSEMBLY	ARTICULATING MECHANISM COMPONENTS AND SYSTEM FOR EASY ASSEMBLY AND DISASSEMBLY	LINK SYSTEMS AND ARTICULATION MECHANISMS FOR REMOTE MANIPULATION OF SURGICAL OR DIAGNOSTIC TOOLS	ARTICULATING MECHANISM WITH FLEX-HINGED LINKS
David J. Danitz	David J. Danitz	David J. Danitz	David J. Danitz	David J. Danitz	David J. Danitz, Cameron Dale Hinman	David J. Danitz, Cameron Dale Hinman
200580047097.0	2,588,450	PCT/US2005/033257	11/121,668	60/630,912	2007-527559	2007-527558
9/15/2005	9/15/2005	9/15/2005	5/3/2005	11/24/2004	5/23/2005	5/23/2005
Published	Pending	Nati Ph	Published	Expired	Published	Published

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10112- 708.CN1	10112- 708.601	10112- 708.501	10112- 708.201	10112- 707.JP1	10112- 707.EP1
China	PCT	ASU	USA	Japan	Europe
ARTICULATING MECHANISMS AND LINK SYSTEMS WITH TORQUE TRANSMISSION IN REMOTE MANIPULATION OF INSTRUMENTS AND TOOLS	ARTICULATING MECHANISMS AND LINK SYSTEMS WITH TORQUE TRANSMISSION IN REMOTE MANIPULATION OF INSTRUMENTS AND TOOLS	ARTICULATING MECHANISMS AND LINK SYSTEMS WITH TORQUE TRANSMISSION IN REMOTE MANIPULATION OF INSTRUMENTS AND TOOLS	ARTICULATING MECHANISMS AND LINK SYSTEMS WITH TORQUE TRANSMISSION IN REMOTE MANIPULATION OF INTRUMENTS AND TOOLS	ARTICULATING MECHANISM COMPRISING PAIRS OF LINK COMPONENTS CONNECTED BY CABLES AND WHICH CAN BE EASILY ASSEMBLED	ARTICULATING MECHANISM COMPRISING PAIRS OF LINK COMPONENTS CONNECTED BY CABLES AND WHICH CAN BE EASILY ASSEMBLED
David J. Danitz, Cameron Dale Hinman	David J. Danitz, Cameron Date Hinman	Cameron Date Hinman	David J. Danitz,Cameron Dale Hinman	David J. Danitz	Davld J. Danitz
200580046956.4	PCT/US2005/041663	11/122,598	10/997,372	2007-543030	05798225.8
11/18/2005	11/18/2005	5/4/2005	11/23/2004	9/15/2005	9/15/2005
sued	Natl Ph	Published	Published	Published :	Published

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10112- 709.EP2	10112- 709.EP1	10112- 709.DE1	10112- 709.CN1	10112- 709.601	10112- 709.201	10112- 708.JP1	10112- 708.EP2
Europe	Europe	Germany	China	PCT	USA	Japan	Europe
ARTICULATING SHEATH FOR FLEXIBLE INSTRUMENTS	ARTICULATING MECHANISMS AND LINK SYSTEMS WITH TORQUE TRANSMISSION IN REMOTE MANIPULATION OF INSTRUMENTS AND TOOLS	ARTICULATING MECHANISMS AND LINK SYSTEMS WITH TORQUE TRANSMISSION IN REMOTE MANIPULATION OF INSTRUMENTS AND TOOLS					
David J. Danitz, Cameron Dale Hinman	David J. Danitz, Cameron Dale Himman	David J. Danitz, Cameron Dale Hinman	David J. Danitz, Cameron Dale Hinman				
	05796589,9	05798589.9	200580046957.9	PCT/US2005/033260	10/997,245	2007-543225	08009895.7
7/13/2010	9/15/2005	9/15/2005	9/15/2005	9/15/2005	11/23/2004	11/18/2005	11/18/2005
Pending	Reg Ph	Issued	Published .	Natl Ph	Published	Published	Published

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7/21/2010	PCT/US2010/042685	Cameron Dale Hinman	ARTICULATING MECHANISM	PCT	10112- 714.600
	12/508,478	Cameron Dale Hinman	ARTICULATING MECHANISM	USA	10112- 714.200
	12/542,589	Lewis Isbell, Jr.	INSTRUMENT WITH ARTICULATION LOCK	USA	10112- 713.200
	61/089,761	Lewis Isbell, Jr.	INSTRUMENT WITH ARTICULATION LOCK	USA	10112- 713.100
	61/089,748	Lewis Isbell, Jr.	INSTRUMENT WITH ARTICULATION LOCK	USA	10112- 712.100
9/15/2005	2007-543031	David J. Danitz, Cameron Dale Hinman	ARTICULATING SHEATH FOR FLEXIBLE INSTRUMENTS	Japan	10112- 709.JP1
9/15/2005	05798589.9	David J. Danitz, Cameron Dale Hinman	ARTICULATING SHEATH FOR FLEXIBLE INSTRUMENTS	Italy	10112- 709.IF1
9/15/2005	1970/KOLNP/2007	David J. Danitz, Cameron Dale Hinman	ARTICULATING SHEATH FOR FLEXIBLE INSTRUMENTS	India	10112- 709.IN1
9/15/2005	6.68596250	David J. Danitz, Cameron Dale Hinman	ARTICULATING SHEATH FOR FLEXIBLE INSTRUMENTS	United Kingdom	10112- 709.GB1
9/15/2005	05796589.9	David J. Danitz, Cameron Dale Hinman	ARTICULATING SHEATH FOR FLEXIBLE INSTRUMENTS	France	10112- 709.FR1
		David J. Danitz, Cameron Dale Hinman	ARTICULATING SHEATH FOR FLEXIBLE INSTRUMENTS	Europe	10112- 709.EP3

PATENT REEL: 024754 FRAME: 0896

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Publis	12/15/2008 Published	12/335,462	Adam Gold, David J. Danitz	HANDLELESS CLAMPING DEVICE	USA	50651- 20014.12
Publish	12/15/2008 Published	12/335,452	Adam Gold, David J. Danitz	HANDLELESS CLAMPING DEVICE	USA	50651- 20014.11
Publish	12/15/2008 Published	12/335,431	Adam Gold, David J. Danitz	HANDLELESS CLAMPING DEVICE	USA	50651- 20014.10
Issued	3/25/2003	10/397,915	Adam Gold, David J. Danitz	HANDLELESS CLAMPING DEVICE	ASU	50651- 20014.00