

PATENT ASSIGNMENT COVER SHEET

Electronic Version v1.1
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EPAS ID: PAT6387235

SUBMISSION TYPE:	NEW ASSIGNMENT
NATURE OF CONVEYANCE:	ASSIGNMENT
CONVEYING PARTY DATA	
Name	Execution Date
BOARD OF REGENTS OF THE UNIVERSITY OF NEBRASKA	11/14/2017
RECEIVING PARTY DATA	
Name:	VIRTUAL INCISION CORPORATION
Street Address:	2021 TRANSFORMATION DRIVE
Internal Address:	SUITE 1250
City:	LINCOLN
State/Country:	NEBRASKA
Postal Code:	68508
PROPERTY NUMBERS Total: 2	
Property Type	Number
Application Number:	14334383
Application Number:	61847394
CORRESPONDENCE DATA	
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ATTORNEY DOCKET NUMBER:	8966355/102505
NAME OF SUBMITTER:	SEAN SOLBERG
SIGNATURE:	/Sean Solberg/
DATE SIGNED:	11/05/2020
Total Attachments: 4	
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PATENT ASSIGNMENT AGREEMENT

This PATENT ASSIGNMENT AGREEMENT ("Patent Assignment") is made by Board of Regents of the University of Nebraska ("Assignor"), a Nebraska corporate public body, located at Varner Hall, 3835 Holdrege, Lincoln, NE 68583, in favor of Virtual Incision Corporation ("Assignee"), a Nebraska corporation located at 2021 Transformation Drive, Suite 1250, Lincoln, NE 68508.

WHEREAS, Assignor has agreed to execute and deliver this Patent Assignment, for recording with the United States Patent and Trademark Office and corresponding entities or agencies in any applicable jurisdictions;

NOW THEREFORE, the parties agree as follows:

1. Assignment. For good and valuable consideration, the receipt and sufficiency of which are hereby acknowledged, Assignor hereby irrevocably conveys, transfers and assigns to Assignee, and Assignee hereby accepts, all of Assignor's right, title and interest in and to the following (the "Assigned Patents"):

(a) the patents and patent applications set forth in Schedule I hereto and all issuances, divisions, continuations, continuations-in-part, reissues, extensions, reexaminations and renewals thereof (the "Patents");

(b) all foreign counterparts of the Patents and all pending applications therefore, including all rights of any kind whatsoever of Assignor accruing under any of the foregoing provided by applicable law of any jurisdiction, by international treaties and conventions and otherwise throughout the world;

(c) any and all royalties, fees, income, payments and other proceeds now or hereafter due or payable with respect to any and all of the foregoing; and

(d) any and all claims and causes of action with respect to any of the foregoing, whether accruing before, on or after the date hereof, including all rights to and claims for damages, restitution and injunctive and other legal and equitable relief for past, present and future infringement, misappropriation, violation, misuse, breach or default, with the right but no obligation to sue for such legal and equitable relief and to collect, or otherwise recover, any such damages.

2. Recordation and Further Actions. Assignor hereby authorizes the Commissioner for Patents in the United States Patent and Trademark Office and the officials of corresponding entities or agencies in any applicable jurisdictions to record and register this Patent Assignment upon request by Assignee. Following the date hereof, Assignor

shall take such steps and actions, and provide such cooperation and assistance to Assignee and its successors, assigns and legal representatives, including the execution and delivery of any affidavits, declarations, oaths, exhibits, assignments, powers of attorney, or other documents, as may be necessary to effect, evidence or perfect the assignment of the Assigned Patents to Assignee, or any assignee or successor thereto.

3. Counterparts. This Patent Assignment may be executed in counterparts, each of which shall be deemed an original, but all of which together shall be deemed to be one and the same agreement. A signed copy of this Patent Assignment delivered by facsimile, e-mail or other means of electronic transmission shall be deemed to have the same legal effect as delivery of an original signed copy of this Patent Assignment.

4. Successors and Assigns. This Patent Assignment shall be binding upon and shall inure to the benefit of the parties hereto and their respective successors and assigns.

5. Governing Law. This Patent Assignment and any claim, controversy, dispute or cause of action (whether in contract, tort or otherwise) based upon, arising out of or relating to this Patent Assignment and the transactions contemplated hereby shall be governed by, and construed in accordance with, the laws of the United States and the State of Nebraska, without giving effect to any choice or conflict of law provision or rule (whether of the State of Nebraska or any other jurisdiction).

[SIGNATURE PAGE FOLLOWS]

IN WITNESS WHEREOF, Assignor has duly executed and delivered this Patent Assignment as of the date set forth below.

Board of Regents of the University of
Nebraska

Signed: *J T CD*

Printed Name: Jesse T. Nish

Title: Director of Intellectual Property

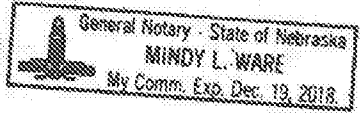
Date: July 11, 2017

Subscribed to and sworn to before me this 11th day of July, 2017.

Signed: *Mindy L. Ware*

Notary Public

Notary Seal



SCHEDULE 1

ASSIGNED PATENTS AND PATENT APPLICATIONS

Country	App. No.	Public. No.	Filing Date	Title
US	13/833,605	20140046340	3/15/2013	ROBOTIC DEVICES WITH ON BOARD CONTROL & RELATED SYSTEMS AND DEVICES ("AlphaBot 2")
CA	2880622	2880622	3/15/2013	ROBOTIC DEVICES WITH ON BOARD CONTROL & RELATED SYSTEMS AND DEVICES ("AlphaBot 2")
EPO	13827150.7	N/A	3/15/2013	ROBOTIC DEVICES WITH ON BOARD CONTROL & RELATED SYSTEMS AND DEVICES ("AlphaBot 2")
JP	2015-526524	N/A	3/15/2013	ROBOTIC DEVICES WITH ON BOARD CONTROL & RELATED SYSTEMS AND DEVICES ("AlphaBot 2")
US	14/212,686	2014/0303434	3/14/2014	ROBOTIC SURGICAL DEVICES, SYSTEMS, AND RELATED METHODS ("AlphaBot 3")
CA	2906772	2906772	3/14/2014	ROBOTIC SURGICAL DEVICES, SYSTEMS, AND RELATED METHODS ("AlphaBot 3")
EPO	14765743.1	2996545	3/14/2014	ROBOTIC SURGICAL DEVICES, SYSTEMS, AND RELATED METHODS ("AlphaBot 3")
JP	2016-502815	N/A	3/14/2014	ROBOTIC SURGICAL DEVICES, SYSTEMS, AND RELATED METHODS ("AlphaBot 3")
US	14/334,383	2015/0051446	7/17/2014	ROBOTIC SURGICAL DEVICES, SYSTEMS AND RELATED METHODS ("Alphabet 3 Improvements")
CA	2918531	2918531	7/17/2014	ROBOTIC SURGICAL DEVICES, SYSTEMS AND RELATED METHODS ("Alphabet 3 Improvements")
JP	2016-527105	N/A	7/17/2014	ROBOTIC SURGICAL DEVICES, SYSTEMS AND RELATED METHODS ("Alphabet 3 Improvements")
EPO	14825872.6	3021779	7/17/2014	ROBOTIC SURGICAL DEVICES, SYSTEMS AND RELATED METHODS ("Alphabet 3 Improvements")
US	14/853,477	2016/0074120	9/14/2015	QUICK-RELEASE END EFFECTOR AND RELATED SYSTEMS AND METHODS
CA	2961213	2961213	9/14/2015	QUICK-RELEASE END EFFECTOR AND RELATED SYSTEMS AND METHODS
EPO	15840040.8	N/A	9/14/2015	QUICK-RELEASE END EFFECTOR AND RELATED SYSTEMS AND METHODS
JP	2017-514416	N/A	9/14/2015	QUICK-RELEASE END EFFECTOR AND RELATED SYSTEMS AND METHODS
US	62/200,563	N/A	8/3/15	ROBOTIC SURGICAL DEVICES, SYSTEMS, AND RELATED METHODS ("AlphaBot 3.1")
US	15/227,813	2017/0035526	8/3/15	ROBOTIC SURGICAL DEVICES, SYSTEMS, AND RELATED METHODS ("AlphaBot 3.1")
INTL	PCT/US16/045436	WO 2017/024081	8/3/15	ROBOTIC SURGICAL DEVICES, SYSTEMS, AND RELATED METHODS ("AlphaBot 3.1")