#### 506391976 12/08/2020

### PATENT ASSIGNMENT COVER SHEET

EPAS ID: PAT6438732

Electronic Version v1.1 Stylesheet Version v1.2

**SUBMISSION TYPE: NEW ASSIGNMENT NATURE OF CONVEYANCE: ASSIGNMENT** 

#### **CONVEYING PARTY DATA**

Name	Execution Date
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TAKASHI SAITOU	10/22/2020
TAKASHI SHINODA	10/14/2020

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#### **PROPERTY NUMBERS Total: 1**

Property Type	Number
Application Number:	17115532

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ATTORNEY DOCKET NUMBER: 4041J-003955-US-CO **NAME OF SUBMITTER: KERI KLATY SIGNATURE:** /kk/ **DATE SIGNED:** 12/08/2020

**Total Attachments: 2** 

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> **PATENT** REEL: 054582 FRAME: 0447 506391976

## 譲渡証

### **ASSIGNMENT**

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譲受者名: Assignee(s):	住所: Address(es):	
DENSO CORPORATION	1-1, Showa-cho, Kariya-city, Aichi-pref., 448-8661 Japan	
as Assignee(s), and corresponding successors, assigns or oth America, and its territories, dependencies and possessions, to	ner legal representatives, the entire right, title and interest, in the United States of certain inventions known as	
発明の名称: ESTIMATION APPARATUS, TE Title of METHOD, AND COMPUTER-R	ATION SYSTEM, TERMINAL POSITION ERMINAL POSITION ESTIMATION READABLE NON-TRANSITORY M STORING CONTROL PROGRAM	
上記発明についての米国登録特許証の出願は、 described in an application for Letters Patent of the United Stat	ies executed	
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発明者はここに付随する添付書面上にリストされます。 inventor(s) listed on the attached sheet which is incorporated h 注記: 上記日本語抄訳は、本書面の理解の助けとして付記しており Note: The above Japanese text is for the purpose of halping the		
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# 譲渡証(続き) ASSIGNMENT (Cont.)

署名: Signature: 第1発明者 First Inventor	Jetsuya Kusumoto Tetsuya KUSUMOTO	署名日: Oct. 22,2020
署名: Signature: 第2発明者 Second Inventor	Takashi Saitou Takashi SAITOU	署名日: Oct、22, 2020
署名: Signature: 第3発明者 Third Inventor	Takashi Shinoda Takashi SHINODA	署名日: 

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**RECORDED: 12/08/2020**