506559531 03/17/2021

PATENT ASSIGNMENT COVER SHEET

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SUBMISSION TYPE:	NEW ASSIGNMENT
NATURE OF CONVEYANCE:	ASSIGNMENT

CONVEYING PARTY DATA

Name	Execution Date
CLOUDMINDS (SHENZHEN) ROBOTICS SYSTEMS CO., LTD.	03/02/2021

RECEIVING PARTY DATA

Name:	CLOUDMINDS ROBOTICS CO., LTD.	
Street Address:	NO. 1508 KUNYANG ROAD	
Internal Address:	2ND FLOOR, BUILDING 2	
City:	MINHANG DISTRICT, SHANGHAI	
State/Country:	e/Country: CHINA	
Postal Code:	201100	

PROPERTY NUMBERS Total: 1

Property Type	Number
Application Number:	16747290

CORRESPONDENCE DATA

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using a fax number, if provided; if that is unsuccessful, it will be sent via US Mail.

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ATTORNEY DOCKET NUMBER:	CU-74521 RJS/MB	
NAME OF SUBMITTER:	ME OF SUBMITTER: RICHARD J. STREIT	
SIGNATURE:	/Richard J. Streit/	
DATE SIGNED:	03/17/2021	

Total Attachments: 3

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PATENT 506559531 REEL: 055624 FRAME: 0856

UNITED STATES OF AMERICA ASSIGNMENT

In consideration of the payment of ASSIGNEE to ASSIGNOR of the sum of One Dollar (\$1.00), the receipt of which is hereby acknowledged, and for other good and valuable consideration.

ASSIGNOR:

CLOUDMINDS (SHENZHEN) ROBOTICS SYSTEMS CO., LTD.

Room 201, Block A, No. 1, Qianwan Road 1, QianbaishenPort Cooperative District, Shenzhen, Guangdong, 518000, China

hereby sells, assigns and transfers to

ASSIGNEE:

CLOUDMINDS ROBOTICS CO., LTD.

2nd Floor, Building 2, No. 1508 Kunyang Road, Minhang District, ShangHai, 201100, China

and the successors, assigns and legal representatives of the ASSIGNEE the entire right, title and interest for the United States and its territorial possessions, and in all foreign countries, including all rights to claim priority, in and to, any and all improvements which are disclosed in the following U.S. applications:

- U.S. Serial No. 15/658,772 filed 07-25-2017, now U.S. Patent No. 9,994,329 issued 06-12-2018 entitled METHOD AND APPARATUS FOR CONTROLLING AIRCRAFT
- U.S. Serial No. 15/722,731 filed 10-02-2017, now U.S. Patent No. 9,949,887 issued 04-24-2018 entitled
 METHOD, DEVICE AND HELMET FOR GUIDING THE BLIND
- 3. U.S. Serial No. 16/576.234 filed 09-19-2019 entitled IMAGE ANNOTATING METHOD AND ELECTRONIC DEVICE
- 4. U.S. Serial No. <u>16/668,647</u> filed <u>10-30-2019</u> entitled

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- METHOD FOR CONTROLLING ROBOT AND ROBOT DEVICE
- U.S. Serial No. 16/678,267 filed 11-08-2019 entitled METHOD FOR WAKING UP ROBOT AND ROBOT THEREOF
- U.S. Serial No. <u>16/679,692</u> filed <u>11-11-2019</u> entitled ARTICLE SEARCHING METHOD AND ROBOT THEREOF
- 7. U.S. Serial No. <u>16/728,325</u> filed <u>12-27-2019</u> entitled
 METHOD FOR TESTING SOFTWARE, AND COMPUTING DEVICE AND
 COMPUTER-READABLE STORAGE MEDIUM THEREOF
- U.S. Serial No. 16/730,361 filed 12-30-2019 entitled
 METHOD FOR CALCULATING AN ARM ANGLE RANGE OF A ROBOT ARM, COMPUTING DEVICE AND ROBOT
- U.S. Serial No. 16/730,575 filed 12-30-2019 entitled
 MOTION PLANNING METHOD FOR ROBOT ARMS, COMPUTING DEVICE AND ROBOT
- 10. U.S. Serial No. <u>16/738,804</u> filed <u>01-09-2020</u> entitled

 METHOD AND APPARATUS FOR TRAINING AN OBJECT IDENTIFICATION NEURAL NETWORK, AND COMPUTER DEVICE
- U.S. Serial No. <u>16/741,326</u> filed <u>01-13-2020</u> emtitled ROBOT CHARACTER SETTING METHOD AND ROBOT
- U.S. Serial No. <u>16/747,290</u> filed <u>01-20-2020</u> entitled ROBOT ROLE SWITCHING METHOD AND ROBOT
- 13. U.S. Serial No. 16/750,355 filed 01-23-2020 entitled METHOD FOR GENERATING TRAINING DATA, IMAGE SEMANTIC SEGMENTATION METHOD AND ELECTRONIC DEVICE
- 14. U.S. Serial No. <u>16/751,879</u> filed <u>01-24-2020</u> entitled METHOD, APPARATUS AND SYSTEM FOR CONTROLLING SMART DEVICE
- 15. U.S. Serial No. 16/808,766 filed 03-04-2020 entitled
 BINOCULAR BRIGHTNESS SENSITIVITY MEASUREMENT METHOD
 BASED ON WEARABLE DISPLAY DEVICE, DEVICE AND MOBILE
 TERMINAL
- 16. U.S. Serial No. <u>16/809,194</u> filed <u>03-04-2020</u> entitled

 PANUM'S AREA MEASUREMENT METHOD, APPARATUS, AND WEARABLE DISPLAY DEVICE
- 17. U.S. Serial No. <u>16/815,840</u> filed <u>03-11-2020</u> entitled DYNAMIC LEARNING METHOD AND SYSTEM FOR ROBOT, ROBOT AND CLOUD SERVER
- 18. U.S. Serial No. 17/032,399 filed 09-25-2020 entitled

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- METHOD FOR DETECTING GRASPING POSITION OF ROBOT IN GRASPING OBJECT
- 19. U.S. Serial No. <u>16/783,476</u> filed <u>02-06-2020</u> entitled NETWORK PATH OPTIMIZATION METHOD AND SYSTEM
- 20. U.S. Serial No. 16/831,724 filed 03-26-2020 entitled
 ROUTE SELECTION METHOD AND APPARATUS BASED ON HYBRID
 RESOURCE, AND SERVER THEREOF
- 21. U.S. Serial No. 16/409.074 filed 05-10-2019, now U.S. Patent No. 10.917.452 issued 02-09-2021 entitled SPEECH CODING ADJUSTMENT METHOD IN Vol.TE COMMUNICATION AND SERVING BASE STATION THEREOF
- 22. U.S. Serial No. <u>16/418.193</u> filed <u>05-21-2019</u>, now U.S. Patent No. <u>10.812.552</u> issued <u>10-20-2020</u> entitled VOLTE COMMUNICATION METHOD AND BASE STATION THEREOF
- 23. U.S. Serial No. 16/420,735 filed 05-23-2019, now U.S. Patent No. 10,623,940 issued 04-14-2020 entitled TERMINAL MOBILITY MANAGEMENT METHOD AND NETWORK DEVICE
- 24. U.S. Serial No. 16/460,392 filed 07-02-2019 entitled TERMINAL ACCESS METHOD AND NETWORK DEVICE

and, in and to, all Letters Patent to be obtained for said invention by the above application or any continuation, division, renewal, or substitute thereof, and as to letters patent any reissue or re-examination thereof.

ASSIGNOR hereby covenants that no assignment, sale, agreement or encumbrance has been or will be made or entered into which would conflict with this assignment and sale.

ASSIGNOR further covenants that ASSIGNEE will, upon its request, be provided promptly with all pertinent facts and documents relating to said invention and said Letters Patent and legal equivalents as may be known and accessible to ASSIGNOR and will testify as to the same in any interference, litigation or proceeding related thereto and will promptly execute and deliver to ASSIGNEE or its legal representatives any and all papers, instruments or affidavits required to apply for, obtain, maintain, issue and enforce said application, said invention and said Letters Patent and said equivalents thereof which may be necessary or desirable to carry out the purposes thereof.

IN WITNESS WHEREOF, I/we have set our hand and seal

<u>∂•J</u> 1-3.2 Date	<u> </u>
	President of CLOUDMINDS (SHENZHEN) ROBOTICS SYSTEMS COLLED

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RECORDED: 03/17/2021