

## PATENT ASSIGNMENT COVER SHEET

Electronic Version v1.1  
Stylesheet Version v1.2

EPAS ID: PAT7689049

<b>SUBMISSION TYPE:</b>	NEW ASSIGNMENT
<b>NATURE OF CONVEYANCE:</b>	ASSIGNMENT
<b>CONVEYING PARTY DATA</b>	
<b>Name</b>	<b>Execution Date</b>
ENERGID TECHNOLOGIES CORPORATION	12/06/2022
<b>RECEIVING PARTY DATA</b>	
<b>Name:</b>	UNIVERSAL ROBOTS USA, INC.
<b>Street Address:</b>	5430 DATA COURT
<b>Internal Address:</b>	SUITE 300
<b>City:</b>	ANN ARBOR
<b>State/Country:</b>	MICHIGAN
<b>Postal Code:</b>	48108
<b>PROPERTY NUMBERS Total: 1</b>	
<b>Property Type</b>	<b>Number</b>
Application Number:	11396272
<b>CORRESPONDENCE DATA</b>	
<b>Fax Number:</b>	
<i>Correspondence will be sent to the e-mail address first; if that is unsuccessful, it will be sent using a fax number, if provided; if that is unsuccessful, it will be sent via US Mail.</i>	
<b>Email:</b>	docketing@burnslev.com
<b>Correspondent Name:</b>	BURNS & LEVINSON, LLP
<b>Address Line 1:</b>	125 HIGH STREET
<b>Address Line 4:</b>	BOSTON, MASSACHUSETTS 02110
<b>ATTORNEY DOCKET NUMBER:</b>	2012320-0000
<b>NAME OF SUBMITTER:</b>	PAUL PYSHER
<b>SIGNATURE:</b>	/Paul Pysher/
<b>DATE SIGNED:</b>	12/12/2022
<b>Total Attachments: 3</b>	
source=2022-12-12 Assignment (Energid to UR USA)#page1.tif	
source=2022-12-12 Assignment (Energid to UR USA)#page2.tif	
source=2022-12-12 Assignment (Energid to UR USA)#page3.tif	

PATENT ASSIGNMENT

WHEREAS, Energid Technologies Corporation (hereafter "Assignor"), a corporation having an address of 213 Burlington Road, Suite 101, Bedford, Massachusetts 01730, United States of America, submits that it is the owner of certain U.S. and foreign patents and applications (listed on the Table attached hereto) (hereafter the "Patent Properties") including by virtue of various Assignments recorded with the Assignment Division of the U.S. Patent and Trademark Office; and

WHEREAS, Universal Robots USA, Inc. (hereafter "Assignee"), a corporation, having an address of 5430 Data Court, Suite 300, Ann Arbor, Michigan 48108, United States of America, desires to acquire all right, title and interest in and to the Patent Properties.

NOW, THEREFORE, for good and valuable consideration, the receipt and sufficiency of which is hereby acknowledged, Assignor does hereby sell, assign, transfer and set over to Assignee, effective as of the execution date hereof, all its right, title and interest in and to the Patent Properties, as well as all right to priority, provisionals, continuations, divisions, and continuations-in-part applications relating to the Patent Properties, and all reissues and extensions thereof, the same to be held and enjoyed by Assignee for its own use and benefit, and for the use and benefit of its successors, assigns, or legal representatives, to the end of the term or terms for which the Patent Properties may be granted or reissued, as fully and entirely as the same would have been held and enjoyed by Assignor if this assignment and sale had not been made.

Assignor also assigns to Assignee, all right, title and interest in and to the inventions and improvements which are subject of, and disclosed in, the Patent Properties throughout the world, including all counterpart international, national, and regional stage priority applications and applications that claim priority to the Patent Properties and the right to file applications and obtain patents, utility models, industrial models and designs for the Patent Properties in its own name throughout the world, including all rights to claim priority based on the filing date of the Patent Properties under the International Convention for the protection of Industrial Property, the Patent Cooperation Treaty, the European Patent Convention, and all other treaties of like purposes, to publish cautionary notices reserving ownership of the inventions and all rights to

register the Patent Properties in appropriate registries; and Assignor further agrees to execute any and all powers of attorney, applications, assignments, declarations, affidavits, and any other papers in connection therewith necessary to perfect such right, title and interest in Assignee.

Assignor also will communicate to Assignee any facts known to it regarding the Patent Properties; and, at the expense of Assignee, will testify in any legal proceedings, sign all lawful papers, execute all provisional, divisional, continuation, continuation-in-part, reissue and substitute applications, make lawful oaths and declarations, and generally do everything possible to vest title in Assignee and to aid Assignee to obtain and enforce proper protection for the Patent Properties in all countries.

This Patent Assignment may be executed in counterparts, each of which shall be deemed an original and all of which, together, shall constitute one and the same instrument.

IN WITNESS WHEREOF, the parties have caused this Patent Assignment to be executed on the dates and in the capacities shown below.

Signature:

DocuSigned by:  
*Ryan Driscoll*  
8E7C9A23BF0B461...

Date: 06-Dec-2022

on behalf of Energid Technologies Corporation  
Ryan E. Driscoll  
Director, Energid Technologies Corporation

Received and acknowledged by:

Signature:

DocuSigned by:  
*Charles J. Gray*  
E724BA0078E346C...

Date: 06-Dec-2022

on behalf of Universal Robots USA, Inc.  
Charles J. Gray  
Director, Universal Robots USA, Inc.

TABLE

<b>JURISDICTION</b>	<b>APPLICATION NUMBER</b>	<b>PATENT NUMBER (IF ISSUED)</b>	<b>SUBJECT MATTER/TITLE</b>
United States	10/408056	6757587	METHOD AND APPARATUS FOR DYNAMICALLY REPROGRAMMING REMOTE AUTONOMOUS AGENTS
United States	11/141843	7680300	VISUAL OBJECT RECOGNITION AND TRACKING
United States	11/396272	8301421	AUTOMATIC CONTROL SYSTEM GENERATION FOR ROBOT DESIGN VALIDATION
United States	12/147863	8408918	METHOD AND APPARATUS FOR HAPTIC SIMULATION
United States	12/620482	8428781	SYSTEMS AND METHODS OF COORDINATION CONTROL FOR ROBOT MANIPULATION
United States	12/435873	9357708	FLEXIBLE ROBOTIC MANIPULATION MECHANISM
United States	14/154873	10078712	DIGITAL PROXY SIMULATION OF ROBOTIC HARDWARE
United States	15/142157	10635761	SYSTEM AND METHOD FOR EVALUATION OF OBJECT AUTONOMY
United States	15/254383	10445442	SYSTEM AND METHOD FOR GAME THEORY-BASED DESIGN OF ROBOTIC SYSTEMS
United States	16/815764	NOT ISSUED	PNEUMATIC HOSE ASSEMBLY FOR A ROBOT