PATENT ASSIGNMENT COVER SHEET

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SUBMISSION TYPE:	NEW ASSIGNMENT
NATURE OF CONVEYANCE:	ASSIGNMENT

CONVEYING PARTY DATA

Name	Execution Date
UBER TECHNOLOGIES, INC.	11/19/2020

RECEIVING PARTY DATA

Name:	UATC, LLC
Street Address:	280 NORTH BERNARDO AVENUE
City:	MOUNTAIN VIEW
State/Country:	CALIFORNIA
Postal Code:	94043

PROPERTY NUMBERS Total: 1

Property Type	Number
Application Number:	17571845

CORRESPONDENCE DATA

Fax Number: (864)233-7342

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using a fax number, if provided; if that is unsuccessful, it will be sent via US Mail.

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Email: usdocketing@dority-manning.com, lglass@dority-manning.com

Correspondent Name: DORITY & MANNING, P.A. AND UATC, LLC

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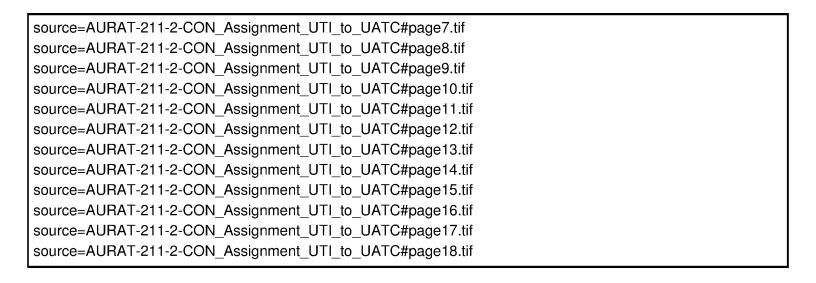
ATTORNEY DOCKET NUMBER:	AURAT-211-2-CON
NAME OF SUBMITTER:	JUSTIN J. BROWN
SIGNATURE:	/Justin J. Brown/
DATE SIGNED:	06/01/2023

Total Attachments: 18

source=AURAT-211-2-CON_Assignment_UTI_to_UATC#page1.tif source=AURAT-211-2-CON_Assignment_UTI_to_UATC#page2.tif source=AURAT-211-2-CON_Assignment_UTI_to_UATC#page3.tif source=AURAT-211-2-CON_Assignment_UTI_to_UATC#page4.tif source=AURAT-211-2-CON_Assignment_UTI_to_UATC#page5.tif source=AURAT-211-2-CON_Assignment_UTI_to_UATC#page6.tif

PATENT REEL: 063820 FRAME: 0579

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PATENT ASSIGNMENT

This Patent Assignment (this "Assignment"), dated and effective as of the latest date of the signatures (the "Effective Date"), is entered into by and between Uber Technologies, Inc., a Delaware corporation ("Uber"), and UATC, LLC, a Delaware limited liability company ("UATC"). Uber and UATC are sometimes referred to herein individually as a "Party" and collectively as the "Parties."

WHEREAS, prior to the Effective Date, Uber, certain of Uber's subsidiaries, and UATC entered into that certain Business Asset Contribution Agreement, dated as of June 30, 2019 (the "Contribution Agreement"), pursuant to which, among other things, Uber contributed, transferred and assigned to UATC all of Uber's right, title and interest in and to the patents and patent applications listed on the attached Exhibit A (the "Transferred Patents").

NOW THEREFORE, for good and valuable consideration, the receipt of which is acknowledged, Uber hereby assigns and transfers to UATC all right, title and interest in and to the Transferred Patents owned by the Uber including in and to any and all divisionals, continuations, continuations-in-part, substitutes, reexaminations, renewals, reissues and patents which have or which may be filed thereon or may be granted therefor, including any and all counterparts worldwide, including all right, title and interest in and to all income, royalties, damages and payments now or hereafter due or payable with respect to the Transferred Patents, and all causes of action (whether in law or equity) and the right to sue, counterclaim, and recover for the past, present and future infringement of the Transferred Patents.

Uber agrees that if requested by UATC, without charge to either of them but at the cost and expense of UATC, Uber will perform any reasonable action which may be necessary to secure and to vest in UATC the full and entire right, title and interest in, to and under the Transferred Patents, including promptly communicating and providing any and all known and accessible facts, data or any other pertinent information thereof and promptly executing and delivering any and all papers, documents, forms, declarations, oaths, affidavits and other legal instruments.

Uber authorizes and requests any official of any country or countries, whose duty it is to issue patents or other evidence or forms of industrial property protection on applications as aforesaid, to issue the same to UATC, its successors, legal representatives and assigns, in accordance with the terms of this instrument.

UBER TECHNOLOGIES, IN	C.
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By:
Name: Keir Gumbs

Title: Associate General Counsel and

Deputy Corporate Secretary

November 19, 2020

UATC, LLC

By: Kin DJ-

Name: Keir Gumbs
Title: Manager

November 19, 2020

TITLE	APPLICATION NUMBER	FILING DATE	PATENT NUMBER	ISSUE DATE	COUNTRY
OBJECT DETECTION BASED ON LIDAR INTENSITY	2019210587	7/31/2019	2019210587	8/6/2020	AU
OBJECT DETECTION BASED ON LIDAR INTENSITY	3,050,586	7/25/2019			CA
AUTONOMOUS VEHICLE COMPUTING SYSTEM, LIGHT DETECTION AND RANGING CALIBRATION SYSTEM AND METHOD THEREOF	201910701809.X	7/31/2019			CN
OBJECT DETECTION BASED ON LIDAR INTENSITY	19189423.7	7/31/2019			EP
AUTONOMOUS VEHICLE COMPUTING SYSTEM, LIGHT DETECTION AND RANGING CALIBRATION SYSTEM AND METHOD THEREOF	42020015496.1	9/7/2020			НК
OBJECT DETECTION BASED ON LIDAR INTENSITY	2019-135337	7/23/2019	6676814	3/16/2020	JP
OBJECT DETECTION BASED ON LIDAR INTENSITY	10201907051S	7/31/2019			GB
AUTONOMOUS VEHICLE WAYPOINT ROUTING	16/173,633	10/29/2018			US

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AUTONOMOUS	16/437,827	6/11/2019	US
VEHICLE			
LOCALIZATION			
USING A LIDAR			
INTENSITY MAP			
ROUTING GRAPH	16/696,227	11/26/2019	US
MANAGEMENT			
IN AUTONOMOUS			
VEHICLE			
ROUTING			
ROUTING GRAPH	PCT/US2019/063	11/26/2019	US
MANAGEMENT	286		
IN AUTONOMOUS			
VEHICLE			
ROUTING			
LOCAL MAP	16/536,925	8/9/2019	US
SERVER AND			
MULTIPLEXER			
LOG	16/366,561	3/27/2019	US
TRAJECTORY			
ESTIMATION FOR			
GLOBALLY			
CONSISTENT			
MAPS			
GROUND	62/835,207	4/17/2019	US
INTENSITY			
LIDAR			
LOCALIZER			
GROUND	16/536,895	8/9/2019	US
INTENSITY			
LIDAR			
LOCALIZER	1.0/800.088	0/10/0010	710
DEPART	16/538,275	8/12/2019	US
CONSTRAINTS			
IMPLEMENTATIO			
NIN			
AUTONOMOUS			
VEHICLE			
ROUTING	(2/924.072	2/27/2010	TIC
DYNAMIC	62/824,973	3/27/2019	US
MATRIX FILTER			
FOR VEHICLE			
IMAGE SENSOR	16/460 431	7/2/2010	TIC
DYNAMIC MATRIX ENTER	16/460,421	7/2/2019	US
MATRIX FILTER			
FOR VEHICLE			
IMAGE SENSOR			

		T		T =
PROACTIVE	62/823,594	3/25/2019		US
GENERATION OF				
TUNING DATA				
FOR				
i e				
AUTONOMOUS				
VEHICLE				
DISPATCH				
PICK-UP/DROP-	62/829,340	4/4/2019		US
OFF ZONE	02/027,540	7/7/2017		05
AVAILABILITY				
ESTIMATION				
USING				
PROBABILITIC				
MODEL				
	16/514 000	7/17/2010		710
PICK-UP/DROP-	16/514,933	7/17/2019		US
OFF ZONE				
AVAILABILITY				
ESTIMATION				
USING				
PROBABILISTIC				
j				
MODEL				
PICK-UP/DROP-	62/829,343	4/4/2019		US
OFF ZONE				
HANDOFF				
BETWEEN				
AUTONOMOUS				
i e				
VEHICLES				
PICK-UP/DROP-	16/514,937	7/17/2019		US
OFF ZONE				
HANDOFF				
BETWEEN				
AUTONOMOUS				
§				
VEHICLES	m.coma.co.co.co.co.co.co.co.co.co.co.co.co.co.	1/24/2020		710
PICK-UP/DROP-	PCT/US2020/015	1/24/2020		US
OFF ZONE	046			
HANDOFF				İ
AUTONOMOUS	16/538,236	8/12/2019	***************************************	US
VEHICLE				
POSITIONING				
į –				
FOR TRIP				
OPTIMIZATION				
GEOREFERENCE	16/366,543	3/27/2019		US
D TRAJECTORY				
ESTIMATION				
SYSTEM				
	(2/940.165	1/20/2010		310
ALL MOVER	62/840,165	4/29/2019		US
PRIORS				
ALL MOVER	16/727,654	12/26/2019		US
PRIORS				
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D	(2/902 779	0/30/2010	l lic
Dynamic Object	62/892,778	8/28/2019	US
Removal	(0/000 557	0/00/0010	II.C
Radar Simulation	62/892,756	8/28/2019	US
Automated	16/553,654	8/28/2019	US
Accuracy			
Assessment in			
Tasking System			
Identifying	62/871,458	7/8/2019	US
Unknown Instances			
for Autonomous			
Driving			
SpAGNN: Spatialy-	62/871,452	7/8/2019	US
Aware Graph Neural			
Networks for			
Relational Behavior			
Forecasting from			
Sensor Data			
End-to-end	62/871,436	7/8/2019	US
Contextual			
Perception and			
Prediction with			
Interaction			
Transformer			
Goal-Directed	62/870,934	7/5/2019	US
Occupancy			
Prediction for Lane-			
Following Actors			
Learning to	62/852,116	5/23/2019	US
Remember from a			
Multi-Task Teacher			
System and Methods	62/866,279	6/25/2019	US
for Autonomous			
Vehicle Testing			
LIDAR FAULT	62/870,183	7/3/2019	US
DETECTION			
SYSTEM			
Systems and	62/882,642	8/5/2019	US
Methods for			
Autonomous			
Vehicle Deployment			
and Control			
Large-Scale Visual	62/822,846	3/23/2019	US
Localization in the			
Age of Self-Driving			
Cars			
Differentiable Deep	62/822,845	3/23/2019	US
PatchMatch for			
Efficient Stereo			
Matching			
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LidarSIM: Realistic	62/822,844	3/23/2019		US
LiDAR Simulation				
by Leveraging the				
Real World				
Learning Joint 2D-	62/822,843	3/23/2019		US
3D Representations				
for Depth				
Completion	********************************			
Deep Stereo Image	62/822,842	3/23/2019		US
Compression				
Learning to Map by	62/822,841	3/23/2019		US
Discovering Lane				
Topology				
Network Automatic	62/822,840	3/23/2019		US
Pruning				
Deformable Filter	62/822,838	3/23/2019		US
Convolution for				
Point Cloud				
Reasoning				
PnPNet: Learning	62/822,837	3/23/2019		US
Temporal Instance				
Representations for				
Joint Perception and				
Motion Forecasting				
PolyTransform:	62/822,836	3/23/2019		US
Deep Polygon				
Transformer for				
Instance				
Segmentation				
Sensor Output	62/870,998	7/5/2019		US
Segmentation				
Systems and	62/821,354	3/20/2019		US
Methods for				
Autonomous				
Vehicles				
Methods and	62/864,843	6/21/2019		US
Systems for Motion	-			
Planning for an				
Autonomous				
Vehicle				
Third-Party Vehicle	62/844,051	5/6/2019		US
Operator Sign-In				
Full Uncertainty for	62/887,760	8/16/2019		US
Motion Planning in				
Autonomous				
Vehicles				
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Hardware in Loop	62/888,034	8/16/2019		US
Testing for				
Generation of				
Latency Profiles for				
Use in Simulation				
Vehicle Integration	62/823,300	3/25/2019		US
Platform (VIP)				
Security Integration				
Vehicle Integration	16/557,084	8/30/2019		US
Platform (VIP)	Í			
Security Integration				
Association and	62/886,001	8/13/2019	 	US
Tracking for		0,11,101		0~
Autonomous				
Devices				
Methods and	62/833,401	4/12/2019		US
Systems for	02/025,701	1712/2019		
Managing Network				
Resources of an				
Autonomous				
Vehicle				
Methods and	16/458,952	7/1/2019		US
j	10/430,932	1/1/2019		0.5
Systems for				
Managing Network Resources of a				
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Vehicle	(2/922 202	4/10/2010		TIC
Methods and	62/833,392	4/12/2019		US
Systems for				
Configuring				
Autonomous-				
Vehicle				
Communications				
Methods and	16/458,353	7/1/2019		US
Systems for				
Configuring Vehicle				
Communications				
Cloud Software	16/526,079	7/30/2019		US
Development Kit for				
Third-Party				
Autonomous				
Vehicles				
Offboard Vehicle	16/517,861	7/22/2019		US
Service Testing				
System				
Systems and	62/863,566	6/19/2019		US
Methods for				
Autonomous				
Vehicle Control				
with Interactive				
Object Annotation				
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O 1 T 11	Z0/007 777	0/1//0010	TIC .
Command Toolbox	62/887,777	8/16/2019	US
For Autonomous			
Vehicles			
Motion Prediction	16/506,522	7/9/2019	US
for Autonomous			
Devices			
Systems and	62/839,127	4/26/2019	US
Methods for			
Improved			
Monitoring of a			
Vehicle Integration			
Platform			
Systems and	16/454,624	6/27/2019	US
Methods for	10/451,021	0/27/2019	
Improved			
Monitoring of a			
Vehicle Integration			
Platform	1.6/1.81.8000		770
Vehicle Integration	16/454,700	6/27/2019	US
Platform (VIP)			
Security			
End-To-End	16/541,739	8/15/2019	US
Interpretable Motion			
Planner for			
Autonomous			
Vehicles			
Multi-Task Multi-	62/858,489	6/7/2019	US
Sensor Fusion for	02/02/0,10/	01772015	
Three-Dimensional			
Object Detection			
System And Method	62/869,251	7/1/2019	US
	02/009,231	1/1/2019	US
For Identifying			
Travel Way Features			
for Autonomous			
Vehicle Motion			
Control			
Deep Structured	62/851,753	5/23/2019	US
Scene Flow for			
Autonomous			
Devices			
Deep Structured	16/531,720	8/5/2019	US
Scene Flow for			
Autonomous			
Devices			
Feature	62/846,248	5/10/2019	US
Compression and	10,510,510	0,23,2025	
Localization for			
Autonomous			
1			
Devices	J	L	

	(2/020 (552	1.45.60.10	T	T	1 770
Image Based	62/829,672	4/5/2019			US
Localization System					<u> </u>
Systems and	62/834,596	4/16/2019			US
Methods for					
Generating					
Synthetic Light					
Detection and					
Ranging Data Via					
Machine Learning					
Systems and	16/299,527	3/12/2019			US
Methods for					
Detecting an Object					
Velocity					
LOCATION-	PCT/US2019/045	8/8/2019			WO
BASED	662				
CHECKLIST					
INTERFACE FOR					
AUTONOMOUS					
VEHICLE USERS					
Gridlock Solver for	PCT/US2019/035	6/6/2019			WO
Motion Planning	713	0,0/2015			''
System of an	/13				
Autonomous					
Vehicle					
STEERABLE	PCT/US2019/047	8/19/2019	 		WO
CAMERA FOR	102	0/19/2019			WU
PERCEPTION	1.02				
AND VEHICLE					
CONTROL					
	16/500 010	7/04/2010	10027707	11/17/2020	TIC
DETECTING AND	16/520,812	7/24/2019	10837786	11/17/2020	US
TRACKING					
LIDAR CROSS-					
TALK	TO COST A TO COST OF THE PARTY	6/11/19/01/0			1710
SYSTEM AND	PCT/US2019/037	6/14/2019			WO
METHOD FOR	222				
DETERMINING					
OBJECT					
INTENTION					
THROUGH					
VISUAL					
ATTRIBUTES			ļ		<u> </u>
Multi-Task	16/420,686	5/23/2019			US
Machine-Learned					
Models for Object					
Intention					
Determination in					
Autonomous					
Driving					

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Methods and	16/437,227	6/11/2019	US
Systems for			
Configuring and			
Instructing			
Autonomous			
Vehicles	******************************		
Autonomous	16/446,021	6/19/2019	US
Vehicle Fleet			
Management for			
Improved			
Computational			
Resource Usage			
LIDAR SYSTEM	PCT/US2019/043	7/25/2019	WO
DESIGN TO	410		
MITIGATE LIDAR			
CROSSTALK			
LIDAR SYSTEM	16/520,799	7/24/2019	US
DESIGN TO			
MITIGATE LIDAR			
CROSS-TALK			
Systems and	PCT/US2019/035	6/5/2019	WO
Methods for	582		
Pipelined Processing			
Of Sensor Data			
Using Hardware			
Palette System for	PCT/US2019/044	7/31/2019	WO
Cargo Transport	419		
Integration Platform	PCT/2019US/043	7/26/2019	WO
for Autonomous	664	,,_0,_0	
Vehicles			
Providing	PCT/US2019/039	6/27/2019	WO
Actionable	529		
Uncertainties in			
Autonomous			
Vehicles			
AUTOMATED	PCT/US2019/032	5/17/2019	WO
DELIVERY	781		🍑
SYSTEMS FOR			
AUTONOMOUS			į
VEHICLES			
Autonomous	PCT/US2019/026	4/11/2019	WO
Vehicle Control	918		
Using Service Pools			
Across Different			
Service Entities			
Autonomous	16/382,657	4/12/2019	US
Vehicle Control			
Using Service Pools			į
Across Different			
Service Entities			
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Autonomous		4/11/2019	CA
Vehicle Control			
Using Service Pools			
Across Different			
Service Entities			
Three-Dimensional	16/353,463	3/14/2019	US
Object Detection			
Three-Dimensional	16/353,457	3/14/2019	US
Object Detection			
Selective Activation	16/414,144	5/16/2019	US
of Autonomous			
Vehicles			
Autonomous	PCT/US2019/043	7/23/2019	WO
Vehicle Idle State	000		
Task Selection for			
Improved			
Computational			
Resource Usage			
Autonomous	16/519,727	7/23/2019	US
Vehicle Idle State			
Task Selection for			
Improved			
Computational			
Resource Usage			
Reducing	PCT/US2019/030	5/2/2019	WO
Autonomous	430		
Vehicle Downtime			
and Idle Data Usage			
Reducing	16/401,629	5/2/2019	US
Autonomous			
Vehicle Downtime			
and Idle Data Usage			
Reducing	16/401,615	5/2/2019	US
Autonomous			
Vehicle Downtime			
and Idle Data Usage			
Reducing		5/2/2019	EP
Autonomous			
Vehicle Downtime			
and Idle Data Usage			
Systems and	PCT/US2019/029	4/26/2019	WO
Methods for	320		
Managing Space at a			
Location for			
Receiving Assets			
Receiving Assets	L	L	 

SYSTEMS AND	PCT/US2019/029	4/26/2019			WO
METHODS FOR	317				
CONTROLLING					
AN ARRIVAL OF					
ONE OR MORE					
ASSETS AT A					
LOCATION					
SYSTEMS AND	PCT/US2019/029	4/26/2019			WO
METHODS FOR	367				
CONTROLLING					
MOVEMENT OF					
ASSETS WITHIN					
A TRANSFER					
HUB					
Controlling an	PCT/US2019/026	4/11/2019			WO
Autonomous	916	1,11,2017			''
Vehicle and the	710				
Service Selection of					
an Autonomous					
Vehicle					
Controlling an	16/381,847	4/11/2019			US
Autonomous	10/301,047	4/11/2019			03
Vehicle and the					
Service Selection of					
an Autonomous					
Vehicle					
	16/381,844	4/11/2019			US
Controlling an	10/301,044	4/11/2019			08
Autonomous					
Vehicle and the					
Service Selection of					
an Autonomous					
Vehicle	1.6/201.020	4/11/2010			Y T.E.
Controlling an	16/381,839	4/11/2019			US
Autonomous					
Vehicle and the					
Service Selection of					
an Autonomous					
Vehicle	1.6/501.001	5/5/0010			TIO
Systems and	16/504,034	7/5/2019			US
Methods for					
Controlling					
Autonomous			·		
Vehicles that					
Provide a Vehicle					
Service to Users					ļ
Lidar Sensor	29/692,678	5/28/2019	USD882430	4/28/2020	US

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Context-Specific	16/553,929	8/28/2019	US10571922	2/25/2020	US
Tolerance for					
Motion Control in					
Autonomous					
Vehicles					W 16 24
Supervised	16/429,847	6/3/2019			US
Movement of					
Autonomous					
Vehicle		ļ			
LIDAR SENSOR	PCT/US2019/032	5/15/2019			WO
ASSEMBLY	456				
INCLUDING					
DOVETAIL JOINT					
COUPLING					
FEATURES					
System and Methods	US16/544,294	4/19/2019			US
to Enable User					
Control of an					
Autonomous					
Vehicle					
Autonomous	16/429,437	6/3/2019			US
Vehicle Collision					
Mitigation Systems					
and Methods					
Disabling Onboard	16/504,042	7/5/2019			US
Input Devices in an	,				
Autonomous					
Vehicle					
COORDINATING	16/389,360	4/19/2019			US
ON-DEMAND	,				
TRANSPORTATIO					
N WITH					
AUTONOMOUS					
VEHICLES					
Systems and	16/445,187	6/19/2019			US
Methods to Control	?				
Autonomous					
Vehicle Motion					
FPGA Device for	16/377,346	4/8/2019			US
Image Classification		., .,			
Vehicle Control	11201907791W	8/23/2019	<u> </u>		SG
System					
	2010 546222	9/27/2010	<del></del>	<b> </b>	JP
Vehicle Control	2019-546232	8/27/2019			JF
System	10700500 5	0/22/2010			rn
Vehicle Control	18708529.5	8/23/2019			EP
System	1.6/2.62.03.6	0/07/0010	TIO1007000	5/10/2020	Y T.C.
Vehicle Security	16/363,366	3/25/2019	US10659382	5/19/2020	US
System	1 < 1 = 1 = 1 = 1	0/00/2010	-		110
Vehicle	16/554,711	8/29/2019			US
Management System					<u>l</u>

Vehicle	11201905385R	6/13/2019	T	T	Tec
	11201905385K	0/13/2019			SG
Management System Vehicle	2019-531719	6/13/2019			JP
Management System	2019-551719	6/13/2019	Table 1		JP
Vehicle	17823305.2	7/12/2019			EP
į.	17823303.2	//12/2019			EP
Management System	201700004401.0	7/24/2010			- Chi
Vehicle	201780084481.0	7/24/2019			CN
Management System					
Vehicle	3047095	6/13/2019			CA
Management System					
Vehicle Servicing	11201905372S	6/13/2019			SG
System					
Vehicle Servicing	17825340.7	7/12/2019			EP
System					
Vehicle Servicing	201780083981.2	7/18/2019		7/30/2020	CN
System					
Vehicle Servicing	3047086	6/13/2019			CA
System		0,111,111			
Charge Control	16/369,460	3/29/2019			US
System for Mobile		,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,			
Energy Storage					
Fleet					
Charge Control	16/369,454	3/29/2019		-	US
System for Mobile					
Energy Storage					
Fleet					
Charge Control	18709119.4	7/22/2019			EP
System for Mobile					
Energy Storage					
Fleet					
NEURAL	201780064218.5	4/17/2019			CN
NETWORK					
SYSTEM FOR			-		
AUTONOMOUS					
VEHICLE					
CONTROL					
SENSOR	2019-137876	7/26/2019		9/2/2020	JP
CLEANING					
SYSTEM FOR					
VEHICLES					
EXTERNAL	16/504,049	7/5/2019			US
SENSOR					
ASSEMBLY FOR					
VEHICLES					

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TRANSPORT	3040081	4/11/2019			CA
FACILITATION					
SYSTEM FOR					
CONFIGURING A					
SERVICE					
VEHICLE FOR A					
USER					
FACILITATING	16/420,654	5/23/2019			US
RIDER PICK-UP					
FOR A SELF-					
DRIVING					
VEHICLE					
DETECTING	16/414,979	5/17/2019	US10662696	5/26/2020	US
OBJECTS WITHIN		1		3,23,2020	
A VEHICLE IN					
CONNECTION					
WITH A SERVICE					
SELECTING	16/509,168	7/11/2019			US
VEHICLE TYPE	10/302,100	//11/2017			
FOR PROVIDING					
TRANSPORT					
AUTONOMOUS	20159753.1	5/13/2016			EP
VEHICLE	20139733.1	3/13/2010			EF
OPERATED WITH					
GUIDE GUIDE					
ł c					
ASSISTANCE	20159764.8	5/13/2016		ļ	EP
AUTONOMOUS	20139764.8	3/13/2016			EP
VEHICLE					
OPERATED WITH					
GUIDE					
ASSISTANCE	1 (7000 (775 4	7 (10 (001 )		515/2020	DE:
AUTONOMOUS	16793657.4	5/13/2016	6020160359	5/6/2020	DE
VEHICLE			81.2		
OPERATED WITH					
GUIDE					
ASSISTANCE					
AUTONOMOUS	16793657.4	5/13/2016	3295268	5/6/2020	FR.
VEHICLE					
OPERATED WITH					
GUIDE					
ASSISTANCE					
AUTONOMOUS	16793657.4	5/13/2016	3295268	5/6/2020	GB
VEHICLE					
OPERATED WITH					
GUIDE					
ASSISTANCE					

AUTONOMOUS	16793657.4	5/13/2016	3295268	5/6/2020	NL
VEHICLE					
OPERATED WITH			-		
GUIDE					
ASSISTANCE			-		
AUTONOMOUS	10-2017-7035830	5/13/2016			KR
VEHICLE			1		
OPERATED WITH					
GUIDE					
ASSISTANCE					
PROVIDING	16/430,943	6/4/2019			US
REMOTE	,				
ASSISTANCE TO					
AN					
AUTONOMOUS					
VEHICLE					
METHODS,	201480022190.5	3/14/2014			CN
SYSTEMS AND	201100022130.2	2711,2011			l Ci (
APPARATUS FOR					
MULTI-SENSORY					
STEREO VISION					
FOR ROBOTICS					
METHODS,	14770009.0	3/14/2014			EP
SYSTEMS AND	14770009.0	3/14/2014			131
APPARATUS FOR					
MULTI-SENSORY					
STEREO VISION					
FOR ROBOTICS					
METHODS.	2016-502343	3/14/2014	6514681	4/19/2019	JP
SYSTEMS AND	2010-302343	3/14/2014	0314001	4/19/2019	JI
APPARATUS FOR					
ł .					
MULTI-SENSORY					
STEREO VISION					
FOR ROBOTICS	10.0015.7000111	2/14/2014			UD
METHODS,	10-2015-7029111	3/14/2014			KR
SYSTEMS AND			and the second s		
APPARATUS FOR					
MULTI-SENSORY					
STEREO VISION					
FOR ROBOTICS	1.6/500 7000	0/6/0010			7.10
SATELLITE	16/532,789	8/6/2019			US
SIGNAL					
CALIBRATION					
SYSTEM					
TRAVEL TIME	15/610,068	5/31/2017	10810883		US
ESTIMATION		<u></u>			<u> </u>

TELEASSISTANC E DATA ENCODING FOR SELF-DRIVING VEHICLES	15/452,456	3/7/2017	10202126	2/12/2019	US
HYBRID TRIP PLANNING FOR AUTONOMOUS VEHICLES	17844132.5	8/14/2017			EP
HYBRID TRIP PLANNING FOR AUTONOMOUS VEHICLES	16/437,881	6/11/2019	10586458	3/10/2020	US
DESTINATION CHANGES IN AUTONOMOUS VEHICLES	2018266108	5/8/2018			AU
DESTINATION CHANGES IN AUTONOMOUS VEHICLES	3,063,089	5/8/2018			CA
DESTINATION CHANGES IN AUTONOMOUS VEHICLES	11201910272T	5/8/2018			SG
DESTINATION CHANGES IN AUTONOMOUS VEHICLES	16/545,300	8/20/2019			US
AUTONOMOUS VEHICLE ROUTING USING ANNOTATED MAPS	16/519,415	7/23/2019			US
ON-DEMAND TRANSPORT SYSTEM FACILITATING THIRD-PARTY AUTONOMOUS VEHICLES	16/389,794	4/19/2019			US
ON-DEMAND TRANSPORT SYSTEM FACILITATING THIRD-PARTY AUTONOMOUS VEHICLES	PCT/US2019/028 396	4/19/2019			WO

NAVIGATIONAL CONSTRAINTS FOR AUTONOMOUS	16/434,501	6/7/2019		US
VEHICLES				
COMPUTER	16/828,632	3/24/2020		US
SYSTEM FOR				
UTILIZING				
ULTRASONIC				
SIGNALS TO				
IMPLEMENT				
OPERATIONS FOR				
AUTONOMOUS				
VEHICLES				

PATENT REEL: 063820 FRAME: 0598

**RECORDED: 06/01/2023**